Unit Root Test with High-Frequency Data[*]

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Abstract

Deviations of asset prices from the random walk dynamic imply the predictability of asset returns and thus have important implications for portfolio construction and risk management. This paper proposes a real-time monitoring device for such deviations using intraday high-frequency data. The proposed procedures are based on unit root tests with in-fill asymptotics but extended to take the empirical features of high-frequency financial data (particularly jumps) into consideration. We derive the limiting distributions of the tests under both the null hypothesis of a random walk with jumps and the alternative of mean reversion/explosiveness with jumps. The limiting results show that ignoring the presence of jumps could potentially lead to severe size distortions of both the standard left-sided (against mean reversion) and right-sided (against explosiveness) unit root tests. The simulation results reveal satisfactory performance of the proposed tests even with data from a relatively short time span. As an illustration, we apply the procedure to the Nasdaq composite index at the 10-minute frequency over two periods: around the peak of the dot-com bubble and during the 2015-2106 stock market sell-off. We find strong evidence of explosiveness in asset prices in late 1999 and mean reversion in late 2015. We also show that accounting for jumps when testing the random walk hypothesis on intraday data is empirically relevant and that ignoring jumps can lead to different conclusions.

Keywords: Unit root test, random walk, in-fill asymptotic, jumps, GARCH, periodicity, microstructure noise

JEL classification: C12, C22.

1 Introduction

The issue of whether stock prices follow a random walk or a mean-reverting process received considerable attention at the end of the 20th century. Evidence of mean reversion in stock prices or autocorrelation in long-horizon returns has been documented in the stock prices of the US (Fama and French, 1988; Poterba and Summers, 1988; Lo and MacKinlay, 1988)[1] and many other countries (Richards, 1997; Balvers et al., 2000; Chaudhuri and Wu, 2003). There is also a burgeoning research program searching for evidence of asset prices deviating towards an explosive regime (viz. speculative bubbles). It is argued that asset prices are explosive (Diba and Grossman, 1988) in the presence of speculative bubbles, as opposed to being a random walk under normal market conditions. With recently developed bubble identification techniques, the literature presents abundant evidence of explosiveness in asset prices.[2] It is important to note that the empirical evidence of both mean reversion and explosiveness of asset prices is observed from low-frequency (weekly, monthly or quarterly) data.

Several trading strategies have been developed to exploit the mean-reverting behavior (Balvers et al., 2000; Gatev et al., 2006; Serban, 2010) and the explosive dynamics (Brooks and Katsaris, 2005; Guenster and Kole, 2013; Milunovich et al., 2019) of asset prices. These trading strategies are shown to outperform the buy-and-hold strategy, with or without the consideration of transaction costs. They are, however, designed for low-frequency trading, which often requires a long holding period to be profitable. The readily available high-frequency financial data provide a strong motive for investors to extend those strategies to high-frequency settings and trade more frequently. The profitability of such high-frequency trading will rely critically upon having a timely and accurate identification technique for such deviations.

Moreover, deviations from the random walk imply the presence of a nonzero drift in a linear drift diffusion (e.g., Ornstein-Uhlenbeck) process. Laurent and Shi (2020b) show that the presence of a nonzero drift results in the overestimation of the integrated variance using various realized volatility estimators (including jump robust estimators) and a power loss for jump detection procedures. As a remedy, they suggest using centered returns for the calculation of integrated volatilities and the construction of the jump test statistics. An effective tool for identifying such deviations in the high-frequency regime will, therefore, be an essential step for statistically documenting empirical evidence of nonzero drifts in the price dynamics of various assets and hence justifying the need for handling drifts with care.

This paper addresses this need by providing a real-time monitoring technique for deviations of asset prices from the random walk using high-frequency data. The real-time monitoring procedure arises from the unit root testing literature,[3] which started in the late 1970s and was catalyzed by the work of Nelson and Plosser (1982). The view that most economic time series are characterized by stochastic trends has since become

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[1] This finding is, however, subject to criticisms. See Lo and MacKinlay (1988); Richardson (1993); McQueen (1992); Kim et al. (1991); Miller et al. (1994).

[2] See, for example, Brooks and Katsaris (2005); Phillips et al. (2011); Phillips and Yu (2011); Homm and Breitung (2012); Phillips and Yu (2013); Phillips et al. (2015a); Milunovich et al. (2019); Narayan et al. (2016); Shi and Song (2016); Harvey et al. (2019).

[3] See, for example, Dickey and Fuller (1979, 1981); Said and Dickey (1984); Phillips (1987a); Phillips and Perron (1988); Kwiatkowski et al. (1992); Schmidt and Phillips (1992).

prevalent. Despite the popularity of unit root testing, there is a profound concern regarding structural breaks caused by changes in institutional or policy settings (Kim et al., 1991). At the turn of the 20th century, an enormous amount of effort was devoted to tackling this issue, considering different break types (such as breaks in the null or in the alternative, breaks in the mean, trend, or slope, sudden or gradual breaks, and breaks with different magnitudes), known or unknown break dates, and the number of breaks.[4] Although one could employ a procedure to endogenously determine the break dates, some assumptions on the nature of the break must be made for practical implementation.[5] Those assumptions are often critical and could lead to distinct results from those obtained under other choices. The unsatisfactory performance of those tests, therefore, prevents their widespread application.

The technique proposed here utilizes intraday data from a relatively short time interval, which is in sharp contrast to the existing literature that searches for evidence of deviations with low-frequency data and usually over a long time span. Therefore, unlike conventional unit root tests, structural breaks are of less concern for the new test. Additionally, the use of intraday data could potentially enable more effective detection of such deviations. The unit root test for high-frequency data employs in-fill asymptotics, where the sample period N is fixed, and the sampling interval Δ converges to zero. The analysis of a fixed time span and fine sampling intervals is typical in the high-frequency literature (e.g., Merton, 1980; Andersen and Bollerslev, 1998). Moreover, in-fill asymptotics have been shown to provide better approximations to their finite sample counterparts (Yu, 2014; Zhou and Yu, 2015; Jiang et al., 2020, 2018) than long-span ($N \to \infty$) and double asymptotics ($N \to \infty$ and $\Delta \to 0$).

Although the in-fill asymptotics for unit root tests was developed as early as 1987 (Phillips, 1987a; Perron, 1991), there have been very few attempts at applying the test to high-frequency data over the past three decades. This is partially due to the paper by Shiller and Perron (1985), who show through simulations that the power of the conventional unit root tests increases with the time span but not with the sampling frequency. More importantly, bringing unit root tests to the high-frequency data context is nontrivial. There are many stylized facts of high-frequency financial data, namely jumps (Andersen et al., 2007a; Lee and Mykland, 2008), conditional heteroskedasticity (Engle, 1982; Bollerslev, 1986; Taylor, 1994), microstructure noise (Aït-Sahalia et al., 2005; Ait-Sahalia and Yu, 2009) and intraday periodicity (Taylor and Xu, 1997; Andersen and Bollerslev, 1997), which may potentially affect the performance and limit theory of the test.

The main focus of this paper is on the effect of jumps on unit root tests. The presence of jumps in high-frequency data has now been widely recognized in the literature.[6] In the empirical application, we identified 149 jumps in the 10-minute Nasdaq log prices around the peak of the dot-com bubble (from May 1999 to June 2000) and 91 jumps from May 2015 to Jan 2016, with their locations displayed in Figure 8. Some of the jumps identified are of a very large magnitude. The occurrence of jumps might be due to macroeconomic news and

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[4]See Perron (1989, 1990); Banerjee et al. (1992); Perron (1997); Lumsdaine and Papell (1997); Vogelsang and Perron (1998); Clemente et al. (1998); Zivot and Andrews (2002); Kim et al. (2002); Lee and Strazicich (2003); Enders and Lee (2012), among others.

[5]See, for example, Amsler and Lee (1995); Vogelsang and Perron (1998); Lee and Strazicich (2001); Chong (2001); Harvey et al. (2001); Saikkonen and Lütkepohl (2002).

[6]See Mancini (2011) for a review on jumps in high-frequency financial data.

company-specific announcements such as share buybacks (Lee, 2012; Bajgrowicz et al., 2015). We show both asymptotically and by simulations that ignoring the presence of jumps leads to a severe size distortion for the Dickey-Fuller (DF) test, depending on the number, locations, and magnitudes of jumps. Specifically, we account for the presence of jumps by including a set of jump dummies in the model (assuming jumps are predetermined) and provide limiting distributions of the DF statistic under the null of a random walk with or without jumps. The limiting distribution of the DF statistic under the unit root null with jumps (i.e., Υ_3 in (16)) differs substantially from the one derived under the null without jumps (i.e., Υ_1 in (6)), suggesting a size distortion of the DF test in the presence of jumps.

The proposed procedure takes the presence of jumps in high-frequency data into consideration. The test statistic, referred to as DF^J and defined formally in (13), is constructed similarly to the DF statistic but from a regression model with jump dummies. We derive the limiting distribution of DF^J under both the null of a random walk with jumps and the alternative of mean reversion or explosiveness (with jumps). Additionally, while the DF test has a size distortion in the presence of jumps, the DF statistic coupled with Υ_3 (instead of Υ_1), referred to as the $DF(J)$ test, could provide correct sizes and hence serve as an alternative unit root test for high-frequency data. We derive the limiting distribution of the DF statistic under the alternative when jumps are present. The DF^J and $DF(J)$ tests assume the number and locations of jumps are known and hence are infeasible. We consider feasible versions of the DF^J and $DF(J)$ tests, which rely on a test to identify jumps. The infeasible and feasible tests have identical limiting properties. The limiting distributions of the test statistics under the alternative depend on the magnitude of the deviation from a random walk, as well as the locations and sizes of the jumps. Under the in-fill asymptotic scheme, the unit root tests are not consistent as the alternative is local by construction.

In the simulations, we show that in the presence of jumps, the conventional unit root test (which ignores jumps) is undersized for the mean reversion alternative and oversized for the alternative of an explosive process. In contrast, the new tests, which account for the presence of jumps, have satisfactory finite sample performance. The empirical sizes are close to the nominal sizes, while the powers of the new tests are reasonably high even for very small deviations from the random walk. Moreover, the presence of conditional heteroskedasticity, intraday periodicity in volatility and microstructure noise does not affect the performance of the tests when the test window is one quarter or longer and the sampling frequency is 10 minutes or lower. Furthermore, we show that although the power of $DF(J)$ is higher than DF^J under certain parameter settings, the right-sided $DF(J)$ test has a high probability of rejecting the null against the explosive alternative when the process is stationary (but very close to a random walk) with jumps and N is relatively low. Therefore, we recommend the use of the DF^J test for empirical applications.

Finally, we apply the $DF^{\hat{J}}$ test (a feasible version of DF^J), along with the conventional unit root test, to 10-minute log prices of the Nasdaq composite index around the peak of the dot-com bubble (1999-2000) and the 2015-2016 sell-off periods. We find cases where different conclusions are drawn from DF and $DF^{\hat{J}}$. We attribute these differences to the lack of power of the left-sided DF test and the oversize of the right-

sided DF test when jumps are ignored. Moreover, there are several interesting empirical findings. First, we find evidence of deviations from the random walk hypothesis to the explosive direction in late 1999 and to the stationary direction in late 2015. Second, our findings show that the dynamic of the log Nasdaq price switches back to a random walk (from being explosive) as it approaches the peak of the bubble episode. This finding suggests that the $DF^{\hat{J}}$ test could potentially enable investors to withdraw from the market before it collapses. Third, while the dot-com bubble bursts in a random walk fashion, the stock market crash in late 2015 follows a mean-reverting pattern. The last finding provides empirical support for the mildly stationary process of Phillips and Shi (2018) and the random drift martingale process of Phillips and Shi (2019) for crashes.

This paper is closely related to the work of Tao et al. (2019), Kim and Park (2019), and Jiang et al. (2018). Tao et al. (2019) propose new tests for the identification of extreme behaviors in asset prices using high-frequency data. Kim and Park (2019) proposes using the conventional unit root tests for the identification of mean-reverting behaviors and applying unit root tests to Lamperti-transformed data series to distinguish stationary and nonstationary processes. Jiang et al. (2018) analyzes the behavior of the KPSS stationarity test in a continuous-time framework. However, none of these papers considers the impact of the high-frequency features of financial data (especially jumps) on test performance.

The remainder of the paper is organized as follows. Section 2 revisits the conventional unit root test with in-fill asymptotics under both the null and the alternatives. Section 3 introduces the new unit root tests for intraday high-frequency data, provides the limiting distributions of the new test statistics under both the null and the alternative, and discusses the jump detection procedure. Monte Carlo simulations are conducted in Section 4. An empirical illustration using the Nasdaq stock index is proposed in Section 5. Section 6 concludes the paper. The proofs of theorems are collected in the appendix, while the proofs of lemmas and remarks are presented in an online supplement.

2 Econometric Method

Consider a set of equally spaced data sampled at an interval Δ. The logarithmic price is denoted by $y_{i\Delta}$ with $i = \{1, \ldots, T\}$. The T observations span across $N = T\Delta$ days. The aim is to detect any deviations of $y_{i\Delta}$ from the random walk using intraday data from a fixed time period (N days). Jumps are not considered here but will be introduced in the next section.

2.1 Hypotheses and Model Specifications

The null hypothesis of a unit root is specified as

$$y_{i\Delta} = y_{(i-1)\Delta} + \sigma\sqrt{\Delta}\varepsilon_{i\Delta}, \tag{1}$$

with initial value y_0, where σ is a constant and $\varepsilon_{i\Delta} \overset{i.i.d}{\sim} \mathcal{N}(0,1)$. The alternative hypothesis is

$$y_{i\Delta} = \alpha_0 + \beta_0 y_{(i-1)\Delta} + \lambda_0 \varepsilon_{i\Delta}, \tag{2}$$

where $\alpha_0 = \mu\left(1 - e^{\theta\Delta}\right)$ with μ and θ being constant, $\beta_0 = e^{\theta\Delta}$ and $\lambda_0^2 = \frac{\sigma^2}{2\theta}\left(e^{2\theta\Delta} - 1\right)$. Model (2) is the exact discrete-time solution of the drift-diffusion process

$$dy_t = \theta\left(y_t - \mu\right)dt + \sigma dw_t, \tag{3}$$

where w_t is the standard Wiener process. It reduces to Model (1) when $\theta = 0$. When $\theta \neq 0$, the autoregressive coefficient

$$\beta_0 = 1 + \theta\Delta + O\left(\Delta^2\right)$$

converges to unity at a rate of $\Delta = N/T$. Given that N is fixed, the process is equivalent to the local-to-unity process of Phillips (1987b) in both the explosive (when $\theta > 0$) and mean reversion (when $\theta < 0$) directions.[7]

The regression model used to test the null hypothesis of a unit root includes an intercept and is specified as follows:

$$y_{i\Delta} = \alpha + \beta y_{(i-1)\Delta} + v_{i\Delta}, \tag{4}$$

where $v_{i\Delta}$ is the error term. The Dickey-Fuller statistic is

$$DF = \left(\hat{\beta} - 1\right)\left[\frac{T\sum_{j=1}^T y_{(j-1)\Delta}^2 - \left(\sum_{j=1}^T y_{(j-1)\Delta}\right)^2}{\sum_{j=1}^T \left(y_{j\Delta} - \hat{\alpha} - \hat{\beta}y_{(j-1)\Delta}\right)^2}\right]^{1/2}, \tag{5}$$

where $\hat{\alpha}$ and $\hat{\beta}$ represent the OLS estimates of α and β.

Next, we provide the asymptotic properties of the unit root test under both the null and the alternative.

2.2 Asymptotics under the Null

Lemma 2.1 *Under the null hypothesis (1), as $\Delta \to 0$ ($T \to \infty$ with N fixed):*

$$(a)\ \ y_{T\Delta} \Longrightarrow \sigma N^{1/2}\left(w_1 + \gamma\right) \equiv \sigma N^{1/2}\Psi_1;$$

$$(b)\ \ T^{-1}\sum_{j=1}^T y_{j\Delta} \Longrightarrow \sigma N^{1/2}\left(\int_0^1 w_s ds + \gamma\right) \equiv \sigma N^{1/2}\Psi_2;$$

$$(c)\ \ T^{-1}\sum_{j=1}^T y_{j\Delta}^2 \Longrightarrow \sigma^2 N\left(\int_0^1 w_s^2 ds + \gamma^2 + 2\gamma\int_0^1 w_s ds\right) \equiv \sigma^2 N\Psi_3;$$

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[7]Kim and Park (2019) show that for the drift diffusion process (3), (non-)mean reversion is equivalent to (non-)stationarity. Furthermore, they consider a general null recurrent diffusion process and show that even under this general model setting, one could employ unit root tests to identify mean-reverting behaviors. However, mean reversion is not equivalent to stationarity in the general setting. A process can be nonstationary and mean reverting. Testing for stationarity versus nonstationarity can be achieved by employing the Lamperti transformation before conducting unit root tests.

$$(d)\ T^{-1/2} \sum_{j=1}^{T} y_{(j-1)\Delta} \varepsilon_{j\Delta} \Longrightarrow \frac{1}{2} \sigma N^{1/2} \left(w_1^2 + 2\gamma w_1 - 1 \right) \equiv \sigma N^{1/2} \Psi_4;$$

with $\gamma = \frac{y_0}{N^{1/2}\sigma}$.

Theorem 2.1 *Under the null hypothesis (1) and with regression model (4), when the sampling interval $\Delta \to 0$ and the time span N is fixed, the DF test statistic*

$$DF \xrightarrow{L} \frac{-\Psi_2 w_1 + \Psi_4}{(\Psi_3 - \Psi_2^2)^{1/2}} = \frac{\frac{1}{2} \left(w_1^2 - 1 \right) - w_1 \int_0^1 w_s ds}{\left[\int_0^1 w_s^2 ds - \left(\int_0^1 w_s ds \right)^2 \right]^{1/2}} \equiv \Upsilon_1. \tag{6}$$

The results in Lemma 2.1 are identical to those in Theorem 6.2 of Phillips (1987a). It is repeated here for ease of comparison. Although the asymptotics of the four quantities in Lemma 2.1 depend on the nuisance parameter γ, the test statistic is asymptotically pivotal. Furthermore, the limiting distribution of DF is identical to its long-span asymptotic (see Hamilton, 1994 for a book reference). This is in sharp contrast to the in-fill limits provided by Phillips (1987a) and Perron (1991), which depend on the nuisance parameter γ. This difference arises from the fact that our regression model includes an intercept, whereas there is no intercept in that of Phillips (1987a) and Perron (1991). Suppose that we did not include an intercept in the regression model as in Phillips (1987a) and Perron (1991). Under the null hypothesis of (1), the test statistic

$$DF \xrightarrow{L} \frac{\frac{1}{2} \left(w_1^2 - 1 \right) + \gamma w_1}{\left[\gamma^2 + \int_0^1 w_s^2 ds + 2\gamma \int_0^1 w_s ds \right]^{1/2}}.$$

The proof follows directly from that of Lemma 2.1 and is omitted for brevity.

Remark 2.1 *The null specification (1) can be generalized to allow for an asymptotically negligible drift such that*

$$y_{i\Delta} = \mu \Delta^\eta + y_{(i-1)\Delta} + \sigma \sqrt{\Delta} \varepsilon_{i\Delta},$$

with μ being a constant and $\eta > 1$. The inclusion of the small drift $\mu \Delta^\eta$ does not have any impact on the limiting properties of the DF statistic.

2.3 Asymptotics under Local Alternatives

By recursive substitution, Model (2) becomes

$$y_{i\Delta} = \alpha_0 \frac{1 - e^{i\theta\Delta}}{1 - e^{\theta\Delta}} + \lambda_0 \sum_{j=1}^{i} e^{(i-j)\theta\Delta} \varepsilon_{j\Delta} + e^{i\theta\Delta} y_0. \tag{7}$$

The stochastic component converges to an Ornstein-Uhlenbeck (OU) process in the limit, i.e.,

$$T^{-1/2} \sum_{j=1}^{\lfloor Tr \rfloor} e^{(\lfloor Tr \rfloor - j)\theta \Delta} \varepsilon_{\Delta j} \Longrightarrow J_c(r) = \int_0^r \exp\left(c(r-s)\right) dw_s \ \text{ with } r \in [0,1] \text{ and } c = \theta N,$$

where $\lfloor . \rfloor$ denotes the integer part of the argument.

Lemma 2.2 *Under the alternative of (2), as $\Delta \to 0$ ($T \to \infty$ with N fixed),*

(a) $y_{T\Delta} \Longrightarrow \sigma N^{1/2} \left[\delta\left(1 - e^c\right) + J_c(1) + e^c \gamma\right] \equiv \sigma N^{1/2} \Xi_1;$

(b) $T^{-1} \sum_{i=1}^{T} y_{i\Delta} \Longrightarrow \sigma N^{1/2} \left[\delta + \int_0^1 J_c(r)\, dr + (\gamma - \delta) \dfrac{e^c - 1}{c}\right] \equiv \sigma N^{1/2} \Xi_2;$

(c) $T^{-1} \sum_{i=1}^{T} y_{i\Delta}^2 \Longrightarrow \sigma^2 N \left[\delta^2 + 2\delta(\gamma - \delta) \dfrac{e^c - 1}{c} + (\gamma - \delta)^2 \dfrac{e^{2c} - 1}{2c}\right.$

$$\left. + \int_0^1 J_c(r)^2\, dr + 2\delta \int_0^1 J_c(r)\, dr + 2(\gamma - \delta) \int_0^1 e^{cr} J_c(r)\, dr\right] \equiv \sigma^2 N \Xi_3;$$

(d) $T^{-1/2} \sum_{i=1}^{T} y_{(i-1)\Delta} \varepsilon_{i\Delta} \Longrightarrow \dfrac{\sigma N^{1/2}}{2} \left(\Xi_1^2 - \gamma^2 - 2c\Xi_3 - 1 + 2c\delta\Xi_2\right) \equiv \sigma N^{1/2} \Xi_4,$

with $J_c(r) = \int_0^r \exp\left(c(r-s)\right) dw_s$ and $\delta = \frac{\mu}{N^{1/2}\sigma}$.

Lemma A.1 of Perron (1991) is a special case of Lemma 2.2 with $\mu = 0$. The results in Lemma 2.2 are identical to those reported in Lemma 8.1 of Zhou and Yu (2015).

Theorem 2.2 *Under the alternative hypothesis (2), as $\Delta \to 0$ ($T \to \infty$ with N fixed), the DF statistic has the following limit distribution:*

$$DF \xrightarrow{L} \frac{-\Xi_2 w_1 + \Xi_4}{\left(\Xi_3 - \Xi_2^2\right)^{1/2}} + c\left(\Xi_3 - \Xi_2^2\right)^{1/2} \equiv \Upsilon_1^A,$$

*where Ξ_2, Ξ_3 and Ξ_4 are defined in Lemma 2.2.*

The limiting distribution of the DF statistic (and hence the asymptotic power of the test) depends on the model parameters y_0, N, μ, θ, and σ. This distribution is continuous with respect to θ. Specifically, when $\theta \to 0$, we have $c \to 0$, $J_c(1) \to w_1$, $\Xi_1 \to w_1 + \gamma = \Psi_1$, $\Xi_2 \to \int_0^1 w(r)\, dr + \gamma = \Psi_2$, $\Xi_3 \to \gamma^2 + \int_0^1 w(r)^2\, dr + 2\gamma \int_0^1 w(r)\, dr = \Psi_3$, and $\Xi_4 \to \frac{1}{2}\left(w_1^2 + 2\gamma w_1 - 1\right) = \Psi_4$. It follows that the limiting distribution

$$\Upsilon_1^A = \frac{-\Xi_2 w_1 + \Xi_4}{\left(\Xi_3 - \Xi_2^2\right)^{1/2}} + c\left(\Xi_3 - \Xi_2^2\right)^{1/2} \to \frac{-\Psi_2 w_1 + \Psi_4}{\left(\Psi_3 - \Psi_2^2\right)^{1/2}} = \Upsilon_1.$$

Figure 1 graphs the asymptotic distributions (kernel densities) of the DF statistic for various settings of θ with $N = \{20, 60\}$. We allow θ to take values from -0.02 to 0.02 with an increment of 0.0001. The initial value $y_0 = 6.959$ is the log price of the Nasdaq stock market on January 2, 1996. The parameter $\sigma = 0.009$,

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Figure 1: The asymptotic distributions (kernel densities) of the DF test statistic under the null Υ_1 and the alternatives Υ_1^A for $N = 20$ and 60. The value of θ ranges from -0.02 to 0.02 with an increment of 0.0001. We set $y_0 = 6.959$, $\mu = 0.0002$ and $\sigma = 0.009$.

(a) $N = 20$ (b) $N = 60$
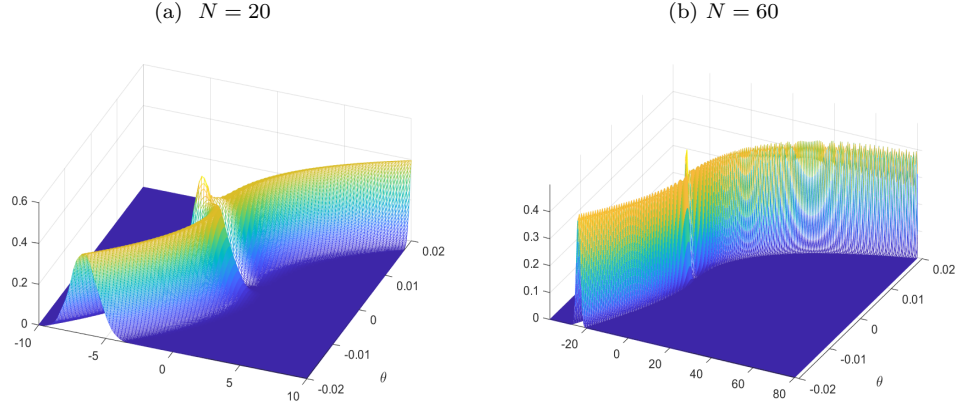
which is the average of the estimated spot volatility for the 10-minute Nasdaq log price from January 2, 1996 to December 8, 2017. The time period N equals one month ($N = 20$) and one quarter ($N = 60$). The distributions are obtained from 10,000 replications, approximating the Wiener process by partial sums of standard normal variates with 10,000 steps. The parameter μ is set to 0.0002. The case of $\theta = 0$ corresponds to the null distribution Υ_1.

First, Υ_1^A is a nonlinear function of θ. When $N = 20$, the shape resembles a 'swimmer' with the peak of the limiting distribution of $\theta = 0$ being the head, those of $\theta > 0$ (resp. $\theta < 0$) forming the right (resp. left) shoulder and arm. The right shoulder and arm are always behind the head, reaching back. That is, when $\theta > 0$, the distribution moves sequentially to the right as θ increases, implying a rising power of the right-tailed unit root test. When $\theta < 0$, the limiting distribution changes in a non-monotonic fashion. It moves first to the right of the null distribution and then gradually to the left as θ deviates further away from zero. The non-monotonicity occurs when θ is very close to zero (viz. the left shoulder) and has an implication for the performance of the tests under this circumstance. In particular, when θ takes a small negative value (e.g., $\theta = -0.001$), with critical values from the null distribution, the probability of (falsely) rejecting the unit root null against an explosive alternative will be non-negligible. In contrast, the chance of correctly rejecting the null against a mean-reverting alternative will be meagre under this setting. This problem disappears when the left arm is ahead of the head (i.e., θ moves further away from zero). Furthermore, from panel (b), the distribution of the DF statistic moves rapidly to the right (resp. left) for positive (resp. negative) θs as the time period N rises to 60. The rate of divergence is faster on the right than on the left.

Remark 2.2 *Under the data generating process (2) and a double asymptotic scheme ($N \to \infty$ and $\Delta \to 0$),*

$$DF \sim \begin{cases} e^{\theta N} \sqrt{\frac{\theta}{2}} \frac{1}{\sigma} |y_0 - \mu + \sigma Z_1| \to +\infty & \text{if } \theta > 0 \\ N^{1/2} \frac{\theta}{\sigma} \left(-\frac{1}{2\theta}\right)^{1/2} \to -\infty & \text{if } \theta < 0 \end{cases},$$

where $Z_1 \sim \mathcal{N}\left(0, \frac{1}{2\theta}\right)$. The proof follows directly from the results of Wang and Yu (2016). See the online supplement for details. The DF statistic diverges to positive and negative infinity when $\theta > 0$ and $\theta < 0$, respectively. This result suggests that one could obtain the asymptotic consistency of the test by allowing the time period N go to infinity. Furthermore, when $\theta > 0$, the divergence rate is exponential, i.e., $O_p\left(e^{\theta N}\right)$. The divergence rate of the DF statistic is $O_p\left(N^{1/2}\right)$ when $\theta < 0$, which is slower than that of DF when $\theta > 0$. This result is consistent with our observation from Figure 1.

3 Unit Root Tests for High-frequency Data

As highlighted in Bauwens et al. (2012), empirical studies have shown that stochastic diffusion models driven by Brownian motion fail to explain some characteristics of asset returns. One of the most important features of financial assets is the presence of discontinuities in prices, also called jumps. See Andersen et al. (2007a) and Lee and Mykland (2008), among others.

Several jump-diffusion processes have been proposed in the literature to account for the presence of either small (infinite activity) jumps or large finite activity jumps. See, for example, Merton (1976); Ahn and Thompson (1988); Kou (2002); Mancini (2011). Here, jumps in log prices are additive and governed by a compound Poisson process J_t as follows

$$dy_t = \theta\left(y_t - \mu\right)dt + \sigma dw_t + dJ_t. \tag{8}$$

The exact discrete time solution of (8) is

$$y_{i\Delta} = \alpha_0 + J_{i\Delta} + \beta_0 y_{(i-1)\Delta} + \lambda_0 \varepsilon_{i\Delta}, \tag{9}$$

where α_0, β_0, and λ_0 are identical to those in (2). The jump component $J_{i\Delta}$ is defined as

$$J_{i\Delta} = \begin{cases} 0 & \text{if there is no jump within the interval } ((i-1)\Delta, i\Delta] \\ \sum_{k=K_{(i-1)\Delta}+1}^{K_{i\Delta}} e^{\theta(i\Delta-\tau_k^s)}\xi_k & \text{if there are jumps within the interval } ((i-1)\Delta, i\Delta], \end{cases}$$

where $K_{i\Delta}$ is the total number of jumps within the interval $[0, i\Delta]$ and follows a Poisson distribution with intensity λ, and τ_k^s is the location of the kth jump. The jump size $\{\xi_k\}$ is a sequence of independent random variables governed by law f, e.g., the lognormal distribution (Merton, 1976) or double exponential distribution (Kou, 2002).

For the unit root tests, we consider a data generating process with a predetermined jump component, as in the recent bubble literature.[8] The total number of jumps and the jump locations are assumed to be known. This assumption is not at all stringent as in practice jumps can be identified before conducting the unit root

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[8]While Blanchard and Watson (1982) and Evans (1991) consider stochastic bubble generating processes where the collapse of bubbles is governed by a Bernoulli process, Phillips et al. (2011) and Phillips et al. (2015a,b) assume deterministic switching points of bubbles for their analysis of bubble origination and termination dates.

tests and with great accuracy. We show in Section 3.2 that the additional jump identification step does not have any asymptotic consequence on the unit root tests and in Section 4 (via Monte Carlo simulations) that the jump identification method advocated in our paper does not distort the finite sample properties of the test.

The total number of jumps within the sample period K is fixed and jump locations are set by parameter $\tau_k = \lfloor r_k T \rfloor$ with $k = 1, \cdots, K$, rather than governed by a Poisson process. Instead of being random quantities, the jump sizes are captured by parameter ϕ_k. The model with predetermined jumps has the form

$$y_{i\Delta} = \alpha_0 + \sum_{k=1}^{K} \phi_k I_{i\Delta}^k + \beta_0 y_{(i-1)\Delta} + \lambda_0 \varepsilon_{i\Delta}, \tag{10}$$

where $\sum_{k=1}^{K} \phi_k I_{i\Delta}^k$ is the jump component. The jump dummy $I_{i\Delta}^k$ is defined as

$$I_{i\Delta}^k = \mathbf{1}(i = \tau_k)$$

with $\mathbf{1}(.)$ being the indicator function. It takes value one at period τ_k when the kth jump occurs and zero otherwise. By construction, $\sum_{i=1}^{T} I_{i\Delta}^k = 1$ (for $k = 1, \ldots, K$) and $\sum_{k=1}^{K} I_{i\Delta}^k = 1$ (for $t = 1, \ldots, T$). The jump component

$$\sum_{k=1}^{K} \phi_k I_{i\Delta}^k = \begin{cases} 0 & \text{if there is no jump at period } i \\ \phi_{k^*} & \text{if the } k^{*\text{th}} \text{ jump occurs at period } i, \end{cases}$$

with $k^* \in [1, K]$. In the special case where the sizes of the jumps are identical, i.e., $\phi_1 = \cdots = \phi_K = \phi$, the jump component

$$\sum_{k=1}^{K} \phi_k I_{i\Delta}^k = \phi \sum_{k=1}^{K} I_{i\Delta}^k = \phi I_{i\Delta}^* \text{ with } I_{i\Delta}^* = \sum_{k=1}^{K} I_{i\Delta}^k.$$

The dummy variable $I_{i\Delta}^*$ takes value one when there is a jump and zero otherwise (i.e., $\sum_{i=1}^{T} I_{i\Delta}^* = K$). By splitting the jump indicator $I_{i\Delta}^*$ into k orthogonal variables $\{I_{i\Delta}^k\}_{k=1}^{K}$, we therefore allow for different jump sizes.

The null hypothesis of a unit root with jumps is

$$y_{i\Delta} = \sum_{k=1}^{K} \phi_k I_{i\Delta}^k + y_{(i-1)\Delta} + \sigma \sqrt{\Delta} \varepsilon_{i\Delta}, \tag{11}$$

and the alternative is (10). We provide the limiting properties of $y_{T\Delta}$, $\sum_{i=1}^{T} y_{i\Delta}$, $\sum_{i=1}^{T} y_{i\Delta}^2$, and $\sum_{i=1}^{T} y_{(i-1)\Delta} \varepsilon_{i\Delta}$ under the null and the alternative in Lemma 3.1 and 3.2, respectively. The proofs of these two lemmas are collected in the online supplement.

Lemma 3.1 *Under the null hypothesis (11), as $\Delta \to 0$ ($T \to \infty$ with N fixed):*

(a) $y_{T\Delta} \implies \sigma N^{1/2}\left(\Psi_1 + \sum_{k=1}^{K} \zeta_k\right) \equiv \sigma N^{1/2}\tilde{\Psi}_1;$

(b) $T^{-1}\sum_{i=1}^{T} y_{i\Delta} \implies \sigma N^{1/2}\left[\Psi_2 + \sum_{k=1}^{K} \zeta_k\left(1 - r_k\right)\right] \equiv \sigma N^{1/2}\tilde{\Psi}_2;$

(c) $T^{-1}\sum_{i=1}^{T} y_{i\Delta}^2 \implies \sigma^2 N\left[\Psi_3 + \Delta_1 + 2\sum_{k=1}^{K} \zeta_k \int_{r_k}^{1} w_s ds + 2\gamma\sum_{k=1}^{K} \zeta_k\left(1 - r_k\right)\right] \equiv \sigma^2 N\tilde{\Psi}_3;$

(d) $T^{-1/2}\sum_{i=1}^{T} y_{(i-1)\Delta}\varepsilon_{i\Delta} \implies \dfrac{\sigma N^{1/2}}{2}\left[\tilde{\Psi}_1^2 - \gamma^2 - 1 - \sum_{k=1}^{K} \zeta_k^2 - 2\sum_{k=1}^{K} \zeta_k\left(w_{r_k} + \gamma + \Delta_2\right)\right] \equiv \sigma N^{1/2}\tilde{\Psi}_4,$

where $\zeta_k = \frac{\phi_k}{\sigma N^{1/2}}$,

$$\Delta_1 = \begin{cases} \zeta_1^2\left(1 - r_1\right) & \text{if } K = 1 \\ \sum_{k=1}^{K-1}\left(r_{k+1} - r_k\right)\left(\sum_{j=1}^{k} \zeta_j\right)^2 + \left(1 - r_K\right)\left(\sum_{j=1}^{K} \zeta_j\right)^2 & \text{if } K > 1 \end{cases},$$

and

$$\Delta_2 = \begin{cases} 0 & \text{if } K = 1 \\ \sum_{j=1}^{k-1} \zeta_j & \text{if } K > 1 \end{cases}.$$

We denote the limiting properties of the above four quantities under the null without jumps (1) by Ψ (with their exact forms in Lemma 2.1) and those under the null with jumps (11) by $\tilde{\Psi}$. It is evident from Lemma 3.1 that the jump component $\sum_{k=1}^{K} \phi_k I_{i\Delta}^k$ has an asymptotic impact on those four quantities. There are additional terms in $\tilde{\Psi}$, relating to the number of jumps K, the jump sizes ϕ_k, and the (fractional) location of the jumps r_k.[9]

Lemma 3.2 *Under the alternative model (10), as $\Delta \to 0$ ($T \to \infty$ with N fixed):*

(a) $y_{T\Delta} \implies \sigma N^{1/2}\left[\Xi_1 + \sum_{k=1}^{K} \zeta_k e^{(1-r_k)c}\right] \equiv \sigma N^{1/2}\tilde{\Xi}_1;$

(b) $T^{-1}\sum_{i=1}^{T} y_{i\Delta} \implies \sigma N^{1/2}\left\{\Xi_2 + \dfrac{1}{c}\sum_{k=1}^{K} \zeta_k\left[e^{(1-r_k)c} - 1\right]\right\} \equiv \sigma N^{1/2}\tilde{\Xi}_2;$

(c) $T^{-1}\sum_{i=1}^{T} y_{i\Delta}^2 \implies \sigma^2 N\left\{\Xi_3 + \Delta_3 + \dfrac{1}{c}\delta\sum_{k=1}^{K} \zeta_k\left[2e^{c(1-r_k)} - 2 - e^{c(2-r_k)} + e^{r_k c}\right]\right.$

$\left. +2\sum_{k=1}^{K} \zeta_k \int_{r_k}^{1} e^{c(r-r_k)}J_c\left(r\right)dr + \dfrac{1}{c}\gamma\sum_{k=1}^{K} \zeta_k e^{r_k c}\left[e^{2c(1-r_k)} - 1\right]\right\} \equiv \sigma^2 N\tilde{\Xi}_3;$

(d) $T^{-1/2}\sum_{i=1}^{T} y_{(i-1)\Delta}\varepsilon_{i\Delta} \implies \dfrac{\sigma N^{1/2}}{2}\left\{\tilde{\Xi}_1^2 - \gamma^2 - 2c\tilde{\Xi}_3 - 1 + 2c\delta\tilde{\Xi}_2 - \sum_{k=1}^{K} \zeta_k^2\right.$

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[9]We assume that there is a finite number of jumps and that the magnitude of the jumps is finite. One could potentially relax this assumption to allow for an infinite number of jumps K or the magnitude of jumps ϕ_k to diverge to infinity or to shrink to zero. We leave these extensions to future research.

$$-2\sum_{k=1}^{K}\zeta_{k}\left[\delta\left(1-e^{r_{k}c}\right)+J_{c}\left(r_{k}\right)+e^{r_{k}c}\gamma+\Delta_{4}\right]\Bigg\}\equiv\sigma N^{1/2}\tilde{\Xi}_{4},$$

where $c=\theta N$, $\delta=\frac{\mu}{N^{1/2}\sigma}$, and

$$\Delta_{3} = \begin{cases} \zeta_{1}^{2}\frac{e^{2c(1-r_{1})}-1}{2c} & if\ K=1 \\ \sum_{k=1}^{K-1}\left(\sum_{j=1}^{k}\zeta_{j}e^{-r_{j}\theta}\right)^{2}e^{2r_{k}\theta}\frac{e^{2\theta(r_{k+1}-r_{k})}-1}{2c}+\left(\sum_{j=1}^{K}\zeta_{j}e^{-r_{j}\theta}\right)^{2}e^{2r_{K}\theta}\frac{e^{2\theta(1-r_{K})}-1}{2c} & if\ K>1 \end{cases},$$

$$\Delta_{4} = \begin{cases} 0 & if\ K=1 \\ \sum_{j=1}^{k-1}e^{(r_{k}-r_{j})\theta}\zeta_{j} & if\ K>1 \end{cases}.$$

Analogously, we use Ξ to denote limiting properties under (2) and $\tilde{\Xi}$ for those under (10). As in Lemma 3.1, the impact of the jump component $\sum_{k=1}^{K}\phi_{k}I_{i\Delta}^{k}$ under the alternative does not disappear in the limit. We observe additional terms in $\tilde{\Xi}$, which depend on the three jump characteristics (i.e., K, ϕ_{K}, and r_{k}) as well as θ and N through the parameter c.

3.1 Unit Root Test with Known Jump Location

For the unit root tests, the jump number K and jump locations τ_{k} are either assumed to be known as a prior or can be identified using a separate procedure with reasonable accuracy. Assume for now that the number of jumps and their locations are known. We consider the latter in Section 3.2. The regression model used to test the null hypothesis of a random walk with jumps is

$$y_{i\Delta}=\alpha+\sum_{k=1}^{K}\phi_{k}I_{i\Delta}^{k}+\beta y_{(i-1)\Delta}+v_{i\Delta}. \tag{12}$$

We use the notation $\tilde{\ }$ to denote the OLS estimates of the model coefficients in (12). The corresponding test statistic, denoted DF^{J}, is

$$DF^{J}=\left(\tilde{\beta}-1\right)\left[\frac{T\sum_{i=1}^{T}y_{(i-1)\Delta}^{2}-\left(\sum_{i=1}^{T}y_{(i-1)\Delta}\right)^{2}}{\sum_{i=1}^{T}\left(y_{i\Delta}-\tilde{\beta}y_{(i-1)\Delta}-\tilde{\alpha}-\sum_{k=1}^{K}\tilde{\phi}_{k}I_{i\Delta}^{k}\right)^{2}}\right]^{1/2}. \tag{13}$$

The limiting distributions of the DF^{J} statistic under both the null and the alternatives are provided below. Moreover, we show the limiting distributions of the DF statistic under the null of (11) and the alternative of (10) (i.e., one ignores the presence of jumps and applies the standard unit root test).

3.1.1 Asymptotics of the DF^J Statistic

Theorem 3.1 *Under the null hypothesis of a random walk with jumps (11), the OLS estimators have the following limiting properties: as $\Delta \to 0$ ($T \to \infty$ with N fixed),*

$$T^{1/2}\left(\tilde{\phi}_k - \phi_k\right) \implies \mathcal{N}(0, \sigma^2 N);$$

$$\tilde{\sigma}_v^2 \to \sigma^2 N,$$

where $\tilde{\sigma}_v^2 = \sum_{i=1}^{T}\left(y_{i\Delta} - \tilde{\beta}y_{(i-1)\Delta} - \tilde{\alpha} - \sum_{k=1}^{K}\tilde{\phi}_k I_{i\Delta}^k\right)^2$. The test statistic DF^J has the following limiting distribution

$$DF^J \implies \frac{-\tilde{\Psi}_2 w_1 + \tilde{\Psi}_4}{\left(\tilde{\Psi}_3 - \tilde{\Psi}_2^2\right)^{1/2}} \equiv \Upsilon_2. \tag{14}$$

Theorem 3.1 suggests that given the exact number of jumps and their location, the estimated jump sizes $\tilde{\phi}_k$ and the error variance $\tilde{\sigma}_v^2$ are consistent. Furthermore, the limiting distribution of DF^J under the new setting (with jumps) is very different from Υ_1 (i.e., in the absence of jumps, see Theorem 2.1). The numerator of Υ_2 can be rewritten as

$$\left[\frac{1}{2}\left(w_1^2 - 1\right) - w_1 \int_0^1 w_s ds\right] + \frac{1}{2}\left[\left(\sum_{k=1}^{K}\zeta_k\right)^2 - \sum_{k=1}^{K}\zeta_k^2\right] - \sum_{k=1}^{K}\zeta_k\Delta_2,$$

and the denominator of Υ_2 is the square root of the following quantity:

$$\left[\int_0^1 w_s^2 ds - \left(\int_0^1 w_s ds\right)^2\right] + \left[\Delta_1 + (1 - r_K)\left(\sum_{j=1}^{K}\zeta_j\right)^2 - \left(\sum_{k=1}^{K}\zeta_k(1 - r_k)\right)^2\right]$$

$$+ 2\left[\sum_{k=1}^{K}\zeta_k \int_{r_k}^1 w_s ds - \int_0^1 w_s ds \sum_{k=1}^{K}\zeta_k(1 - r_k)\right].$$

The limiting distribution of DF^J does not depend on y_0 but on parameters related to jumps, i.e., r_k and ζ_k (including ϕ_k, σ, and N). Next, we simulate the distribution Υ_2. For simplicity, we assume one jump per week such that $K = \lfloor N/5 \rfloor + 1$, $\tau_1 = 1/\Delta$, and $\tau_k = 5(k-1)/\Delta$ for $k > 1$. The sign and magnitude of the jumps are assumed to be the same (i.e., $\phi_k = \phi$). We set $\phi = \{-0.02, -0.01, 0, 0.01, 0.02\}$ and $N = 60$ in the left panel and $N = \{20, 60, 100, 200\}$ and $\phi = 0.02$ in the right panel. We set $\sigma = 0.009$ as in Section 2.3. We see in Figure 2 that Υ_2 is always on the right of Υ_1 and shifts to the right as the magnitude of the jumps increases (regardless of the sign of the jumps) or the time period N expands.

Theorem 3.2 *Under the alternative hypothesis (10), the limiting properties of the OLS estimators are as follows:*

$$T^{1/2}\left(\tilde{\phi}_k - \phi_k\right) \Rightarrow \mathcal{N}(0, \sigma^2 N),$$

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Figure 2: The asymptotic distribution of DF^J (kernel densities) under the null hypothesis of a random walk with jumps. We assume $K = \lfloor N/5 \rfloor + 1$, $\tau_1 = 1/\Delta$, $\tau_k = 5(k-1)/\Delta$ for $k > 1$, and $\phi_k = \phi$. The jump size $\phi = \{-0.02, -0.01, 0.01, 0.02\}$ with $N = 60$ in the left panel and $N = \{20, 60, 100, 200\}$ with $\phi = 0.02$ in the right panel.

(a) $N = 60$ (b) $\phi = 0.02$
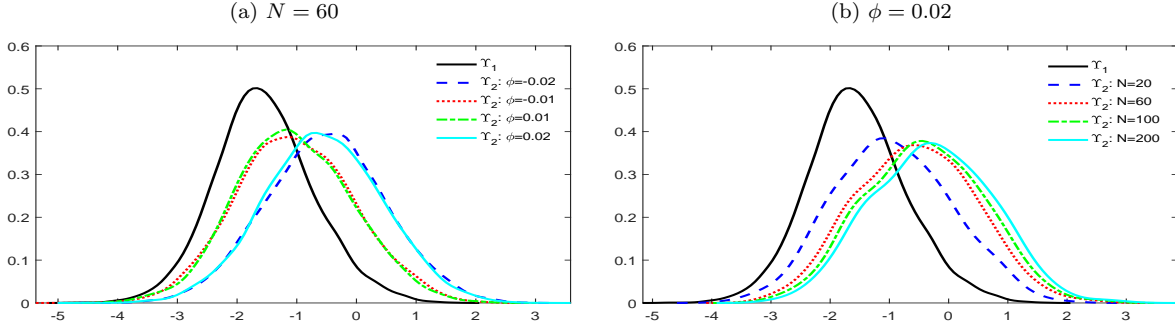
$$\tilde{\sigma}_v^2 \to \sigma^2 N.$$

The test statistic DF^J has the limiting distribution of

$$DF^J \Longrightarrow \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1}{\left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2\right)^{1/2}} + c\left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2\right)^{1/2} \equiv \Upsilon_2^A. \tag{15}$$

Theorem 3.2 shows that under the alternative (10), the OLS estimators $\tilde{\phi}_k$ and $\tilde{\sigma}_\varepsilon^2$ are consistent. The limiting distribution of DF^J depends on θ and N through the parameter c, in addition to the nuisance parameters in Υ_2. We now plot the asymptotic distribution of DF^J against θ with $N = \{20, 60\}$ in Figure 3. To reduce computation, we allow θ to vary from -0.002 to -0.02 on the left and from 0.002 to 0.02 on the right, with an increment of 0.001 (instead of 0.0001 for Figure 1). The setting of jumps is identical to that in Figure 2. The other parameters are the same as those in Figure 1. One can see that the pattern of the DF^J distribution is similar to that of the DF statistic in Figure 1.

For practical implementation, one needs to estimate r_k, ϕ_k and σ before simulating the asymptotic critical values. As shown in Theorem 3.1 and Theorem 3.2, given the locations of the jumps, the magnitude of the jumps ϕ_k can be consistently estimated by OLS with equation (12), while σ^2 can be consistently estimated as

$$\tilde{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{T} \left(y_{i\Delta} - \tilde{\beta} y_{(i-1)\Delta} - \tilde{\alpha} - \sum_{k=1}^{K} \tilde{\phi}_k I_{i\Delta}^k \right)^2 \to \sigma^2$$

under both the null and the alternative. The time period N is known for a given sample. The location of jumps r_k can be identified by the procedure introduced in Section 3.2.1.

Figure 3: The asymptotic distributions (kernel densities) of the DF^J test statistic under the null and the alternative when $N = 20$ and 60. The value of θ ranges from -0.02 to -0.002 on the left and from 0.002 to 0.02 on the right, with an increment of 0.001. We set $y_0 = 6.959$, $\mu = 0.0002$ and $\sigma = 0.009$, $K = \lfloor N/5 \rfloor + 1$, $\tau_1 = 1/\Delta$, $\tau_k = 5(k-1)/\Delta$ for $k > 1$, and $\phi_k = \phi = 0.02$.

(a) $N = 20$ (b) $N = 60$
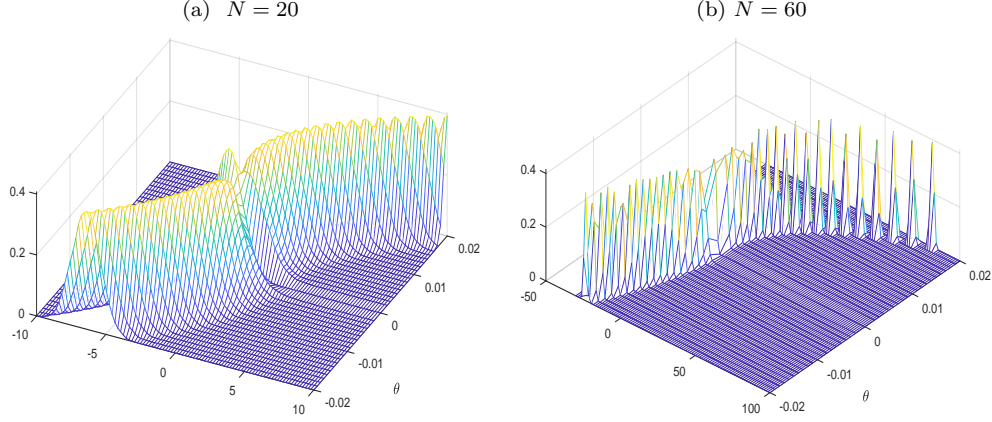
3.1.2   Asymptotic of the DF Statistic in the Presence of Jumps

We first show that the standard unit root test, which compares the DF test statistic with critical values obtained from Υ_1, has incorrect size in the presence of additive jumps.

Theorem 3.3 *Suppose that the data generating process is* (11) *and that one ignores the presence of jumps by estimating Model* (4). *As* $\Delta \to 0$ *($T \to \infty$ with N fixed):*

$$\hat{\sigma}_v^2 = \sum \left(y_{j\Delta} - \hat{\beta} y_{(j-1)\Delta} - \hat{\alpha} \right)^2 \to \sigma^2 N \left(1 + \sum_{k=1}^{K} \zeta_k^2 \right).$$

The DF test statistic has the following limiting distribution:

$$DF \Longrightarrow \frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1 + \sum_{k=1}^{K} \zeta_k \left(w_{r_k} + \gamma + \Delta_2 - \tilde{\Psi}_2 \right)}{\left(1 + \sum_{k=1}^{K} \zeta_k^2 \right)^{1/2} \left(\tilde{\Psi}_3 - \tilde{\Psi}_2^2 \right)^{1/2}} \equiv \Upsilon_3. \tag{16}$$

It is evident from Theorem 3.3 that the estimated model error variance $\hat{\sigma}_v^2$ is inconsistent. The limiting distribution of the DF statistic under (11) is Υ_3, instead of Υ_1. The unit root tests that compare the DF test statistic with critical values from Υ_1 will, therefore, have size distortions. In Figure 4, we simulate Υ_3 and compare it with Υ_1. As before, we set $y_0 = 6.959$, $\sigma = 0.009$, $\phi = \{-0.02, -0.01, 0.01, 0.02\}$ and $N = 60$ in the left panel and $N = \{20, 60, 100, 200\}$ and $\phi = 0.02$ in the right panel. One can see that the distribution of the DF statistic Υ_3 moves to the right of Υ_1 when jumps (both positive and negative) are ignored. This implies that the left-sided DF test is undersized in the presence of jumps, while the right-sided DF test is oversized in the presence of jumps.

    As correctly pointed out by an anonymous referee, one can obtain the correct size for a test using the DF

Figure 4: The asymptotic distributions (kernel densities) of DF under the null hypothesis of a random walk with jumps. We assume $K = \lfloor N/5 \rfloor + 1$, $\tau_1 = 1/\Delta$, $\tau_k = 5(k-1)/\Delta$ for $k > 1$, and $\phi_k = \phi$. The jump size $\phi = \{-0.02, -0.01, 0.01, 0.02\}$ with $N = 60$ in the left panel and $N = \{20, 60, 100, 200\}$ with $\phi = 0.02$ in the right panel.

(a) $N = 60$ (b) $\phi = 0.02$

statistic by constructing critical values from Υ_3 in the presence of jumps, provided consistent estimates of the nuisance parameters and knowledge of jump occurrence. Theorem 3.4 provides the limiting properties of the DF statistic under the alternative with jumps (10).

Theorem 3.4 *Suppose that the data generating process is* (10) *and the regression model is* (4). *As* $\Delta \to 0$ *($T \to \infty$ with N fixed):*

$$\hat{\sigma}_v^2 = \sum \left(y_{j\Delta} - \hat{\beta} y_{(j-1)\Delta} - \hat{\alpha} \right)^2 \to \sigma^2 N \left(1 + \sum_{k=1}^{K} \zeta_k^2 \right).$$

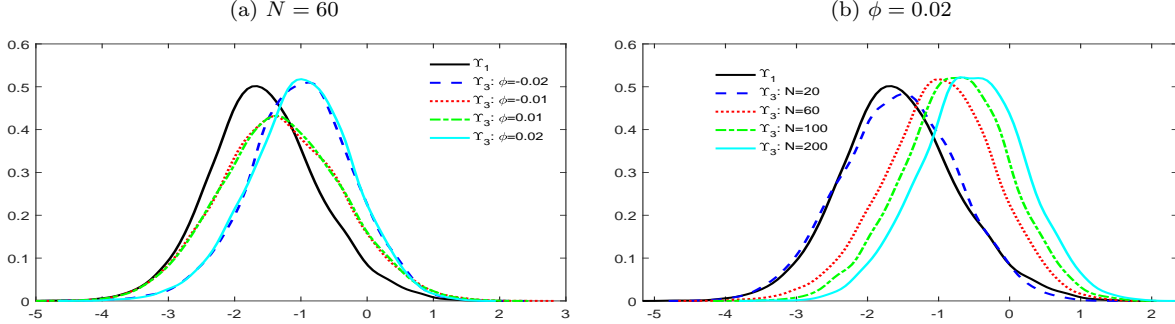*The DF test statistic has the following limiting distribution:*

$$
\begin{aligned}
DF &\implies \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1 + \sum_{k=1}^{K} \zeta_k \left[\delta \left(1 - e^{r_k c} \right) + J_c \left(r_k \right) + e^{r_k c} \gamma + \Delta_4 - \tilde{\Xi}_2 \right]}{\left(1 + \sum_{k=1}^{K} \frac{\phi_k^2}{\sigma^2 N} \right)^{1/2} \left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2 \right)^{1/2}} + c \left(\frac{\tilde{\Xi}_3 - \tilde{\Xi}_2^2}{1 + \sum_{k=1}^{K} \frac{\phi_k^2}{\sigma^2 N}} \right)^{1/2} \\
&\equiv \Upsilon_3^A.
\end{aligned}
$$

It is obvious that σ cannot be consistently estimated with regression (4) in the presence of jumps. To compute critical values from Υ_3, one would need to estimate the nuisance parameters from regression (12) as for the DF^J test.

Recall that the test based on the DF statistic and distribution Υ_1 was denoted by DF. We label the test based on the DF statistic and distribution Υ_3 as $DF(J)$. We use two different notations to highlight the fact that although the two test statistics are identical, the limiting distributions of the test statistic are derived under different specifications of the null (with or without jumps).

The asymptotic distributions of the DF statistic under the null and alternative hypotheses with jumps are presented in Figure 5. The shapes of the density functions are similar to those of the DF and DF^J tests (Figures 1 and 3). In particular, when θ takes negative but small values, the distribution moves to the right

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Figure 5: The asymptotic distributions of the DF test statistic under the null and alternative hypotheses with jumps when $N = 20$ and 60. The value of θ ranges from -0.02 to -0.002 on the left of $\theta = 0$ and from 0.002 to 0.02 on the right, with an increment of 0.001. We set $y_0 = 6.959$, $\mu = 0.0002$ and $\sigma = 0.009$, $K = \lfloor N/5 \rfloor + 1$, $\tau_1 = 1/\Delta$, $\tau_k = 5(k-1)/\Delta$ for $k > 1$, and $\phi_k = \phi = 0.02$.

(a) $N = 20$ (b) $N = 60$
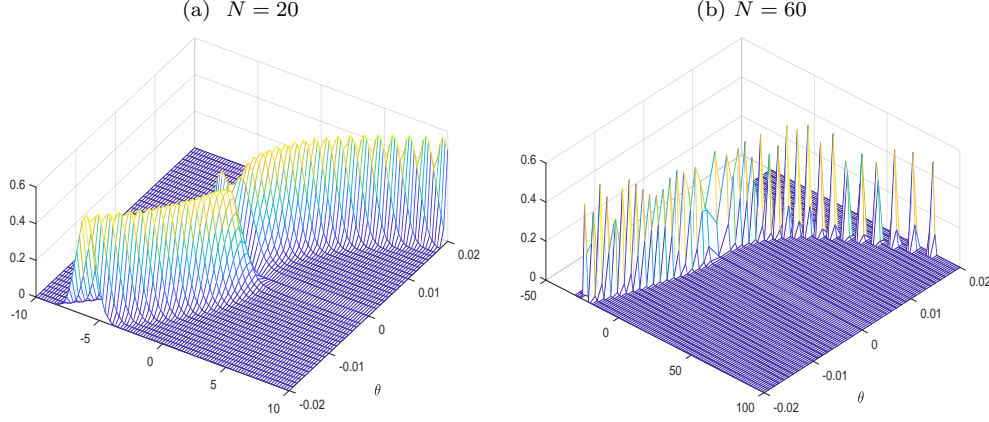
(instead of the left) of the null distribution. As such, the right-sided unit root test might falsely reject the null of unit root against explosiveness when the true θ is negative but very close to zero.

As an illustration, let us consider the case of $\theta = -0.002$. Figure 6 displays the null and alternative limiting distributions of the three approaches (DF, DF^J and $DF(J)$) when $\theta = -0.002$ and $N = \{20, 60\}$. For all three approaches, when $N = 20$, the alternative distribution moves to the right of their null distribution. The movement of Υ_2^A is the least significant, implying the lowest false rejection probability of the right-tailed DF^J test. As the time period increases to 60, the right movements of Υ_1^A and Υ_3^A decrease, whereas the Υ_2^A distribution moves to the left instead. This suggests that unlike the other two methods, the false identification issue of the DF^J test disappears when N increases to 60. The DF^J has a clear advantage over $DF(J)$ in this regard. Consequently, we will focus on DF^J rather than $DF(J)$ to account for jumps in the empirical application and advocate not considering small windows (i.e., $N \leq 20$) with one-sided tests to avoid systematically wrong conclusions.

3.2 Unit Root Test with Unknown Jump Location

We consider a two-step procedure for the case with unknown jumps. The first step is to identify jumps (i.e., total number of jumps $\hat{K}$ and their respective locations $\hat{\tau}_k$ with $k = 1, \ldots, \hat{K}$). The method employed to identify the jumps and the limiting properties of the jump test are discussed in Section 3.2.1. What is important for the second step is to construct a set of jump dummies $\hat{I}_{i\Delta}^k$ (with $k = 1, \ldots, \hat{K}$) such that

$$\hat{I}_{i\Delta}^k = \mathbf{1}\left(i = \hat{\tau}_k\right)$$

which takes value one at period $\hat{\tau}_k$ and zero otherwise. By construction, we have $\sum_{i=1}^{T} \hat{I}_{i\Delta}^k = 1$ for all $k = 1, \ldots, \hat{K}$ and $\sum_{k=1}^{\hat{K}} \hat{I}_{i\Delta}^k = 1$ for all $t = 1, \cdots, T$. In the second step, we conduct the DF^J test by

Figure 6: The null and alternative limiting distributions of the three approaches when $\theta = -0.002$ and $N = \{20, 60\}$: $(\Upsilon_1, \Upsilon_1^A)$ for DF, $(\Upsilon_2, \Upsilon_2^A)$ for DF^J, and $(\Upsilon_3, \Upsilon_3^A)$ for $DF(J)$

(a) $DF : (\Upsilon_1, \Upsilon_1^A)$ and $N = 20$ (b) $DF^J : (\Upsilon_2, \Upsilon_2^A)$ and $N = 20$ (c) $DF(J) : (\Upsilon_3, \Upsilon_3^A)$ and $N = 20$

(d) $DF : (\Upsilon_1, \Upsilon_1^A)$ and $N = 60$ (e) $DF^J : (\Upsilon_2, \Upsilon_2^A)$ and $N = 60$ (f) $DF(J) : (\Upsilon_3, \Upsilon_3^A)$ and $N = 60$
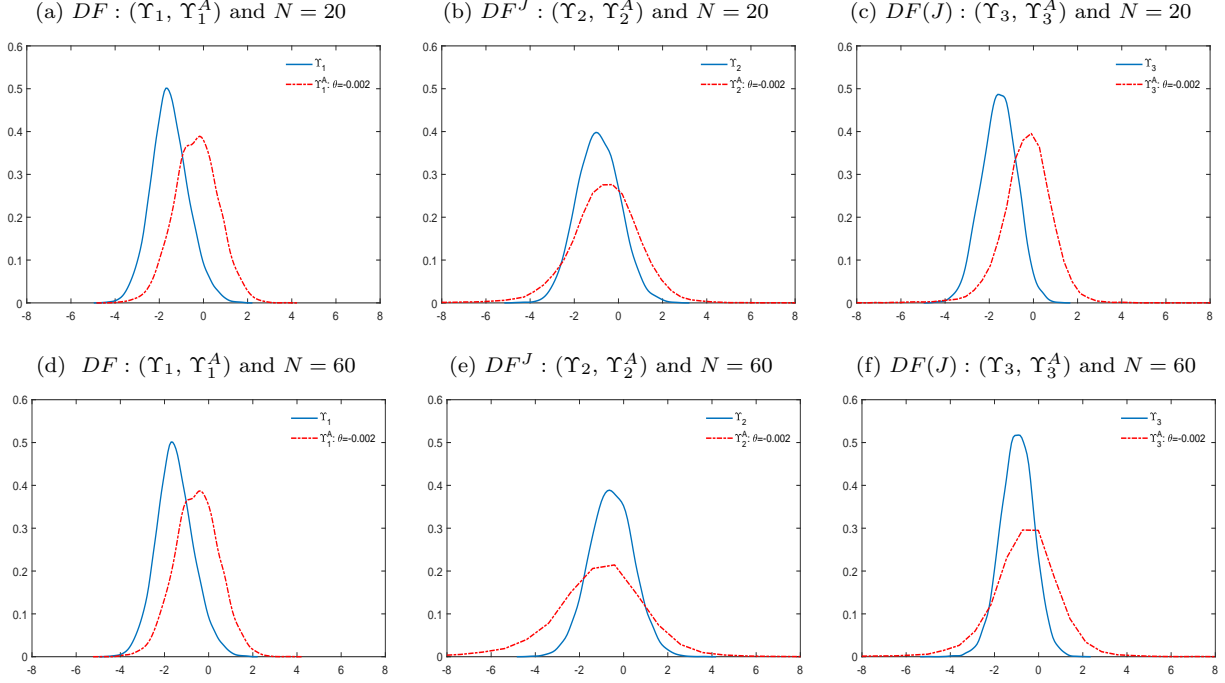
replacing the true jump dummies in regression (12) with the estimated ones. The limiting properties of the feasible version of the DF^J test, denoted by $DF^{\hat{J}}$, are discussed in Section 3.2.2.

3.2.1 Jump Identification

The most popular approach to the estimation of jump arrival time(s) is probably that proposed by Lee and Mykland (2008, LM hereafter). The data generating process under the null hypothesis of no jumps, considered by Lee and Mykland (2008), is

$$dy_t = \mu_t dt + \sigma_t dw_t, \tag{17}$$

where the drift and diffusion coefficients μ_t and σ_t are assumed not to change dramatically over a short time interval. See Lee and Mykland (2008) for further details on the assumptions. This model includes (3) as a special case with $\mu_t = \theta (y_t - \mu)$ and $\sigma_t = \sigma$. Under the alternative,

$$dy_t = \mu_t dt + \sigma_t dw_t + x_t d\tilde{J}_t, \tag{18}$$

where $\tilde{J}_t$ is a counting process independent of w_t and x_t is the jump size, which is assumed to be predictable.

However, the LM jump test suffers from a significant downward size distortion and has low power in finite samples when the drift coefficient μ_t is large in size, as shown by Laurent and Shi (2020b). An example

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given by Laurent and Shi (2020b) is the drift diffusion process (3) with θ and hence the drift coefficient $\mu_t = \theta(y_t - \mu)$ being nonzero.[10] They propose a simple modification to the Lee and Mykland (2008) test and show a dramatic improvement in test performance. As shown in our empirical application, deviations from the random walk (i.e., nonzero θ) are not rare events. It is, therefore, important to account for such a feature and rely on the jump identification procedure of Laurent and Shi (2020b), which is less sensitive to μ_t.

Let $r_{i\Delta} = y_{i\Delta} - y_{(i-1)\Delta}$ denote the log return at time $i\Delta$, $\hat{m}_{i\Delta}$ be the median of the past M log returns (prior to and including the current observation), and $r_{i\Delta}^* = r_{i\Delta} - \hat{m}_{i\Delta}$ be the centered log return. The test statistic of Laurent and Shi (2020b), denoted by $U_{i\Delta}$, is constructed from the centered log returns (instead of the raw return $r_{i\Delta}$ as in Lee and Mykland, 2008) such that

$$U_{i\Delta} = \frac{r_{i\Delta}^*}{\hat{\sigma}_{i\Delta}^*} \text{ with } \hat{\sigma}_{i\Delta}^* = \sqrt{\frac{1}{M}BV_{i\Delta}^*}, \tag{19}$$

where $BV_{i\Delta}^* = \frac{\pi}{2}\frac{M}{M-1}\sum_{j=i-M+2}^{i}|r_{j\Delta}^*||r_{(j-1\Delta)}^*|$ is the bipower variation computed on centered log returns. Under the null hypothesis, the test statistic $U_{i\Delta}$ follows a standard normal distribution Z. As in Lee and Mykland (2008), we reject the null hypothesis of no jump at period $i\Delta$ when $|U_{i\Delta}| > cv_{L,\alpha_L}$, where

$$cv_{L,\alpha_L} = C_L + S_L\beta_L, \tag{20}$$

with $C_L = (2\log L)^{1/2} - \frac{1}{2}(2\log L)^{-1/2}[\log 4\pi + \log(\log L)]$, $\beta_L = -\log[-\log(1 - \alpha_L/2)]$, and $S_L = (2\log L)^{-1/2}$, L being the number of tests conducted. The critical value is derived from extreme value theory for the purpose of controlling for the oversize issue of multiple tests. In all our simulations and the empirical application, we set L to the total number of observations per month (of 20 days) and α_L to 0.75 so that the expected number of spurious detected jumps is one every four months.

Remark 3.1 *Assume that $L \to \infty$ at the same rate of T and $\beta_L \to \infty$ at a rate that is slower than $\sqrt{L\log(L)}$. It follows that*

$$cv_{L,\alpha_L} = C_L + S_L\beta_L = C_L[1 + o_p(1)] = O\left(\sqrt{2\log L}\right) = O\left(\sqrt{-2\log(\Delta)}\right).$$

Furthermore, under the assumption that $M = O(\Delta^a)$ with $-1 < a < -1/2$, we have the asymptotic equivalence of $\hat{\sigma}_{i\Delta}^*$ and $\sigma\sqrt{\Delta}$ (Lee and Mykland, 2008). Suppose that there is a jump at period $i\Delta$. The probability of correctly identifying the jump is

$$P\left(|U_{i\Delta}| > cv_{L,\alpha_L}\right) = P\left(\left|\frac{r_{i\Delta}^*}{\hat{\sigma}_{i\Delta}^*}\right| > cv_{L,\alpha_L}\right) = P\left(|r_{i\Delta}^*| > cv_{L,\alpha_L}\hat{\sigma}_{i\Delta}^*\right)$$

---

[10] A non-zero drift in the continuous time framework does not necessarily imply a non-zero drift in the discrete time framework. Take the OU process (3) and its exact discrete-time solution (2) as an example. Suppose $\mu = 0$ and $\theta \neq 0$. We have the continuous-time drift coefficient $\mu_t = \theta(y_t - \mu) = \theta y_t$ but the discrete time drift $\alpha_0 = \mu(1 - e^{\theta\Delta}) = 0$. The continuous time drift is related to both the intercept and the autoregressive component in the discrete time model.

$$\sim \quad P\left(|r_{i\Delta}^*| > \sigma\sqrt{-2\log\left(\Delta\right)\Delta}\right) = 1 - F_{|r_{i\Delta}^*|}\left(\sigma\sqrt{-2\log\left(\Delta\right)\Delta}\right) \to 1$$

as $\Delta \to 0$, which follows the same argument as in Lee (2012). Now, suppose that there is no jump in period $i\Delta$. The probability of not rejecting the null is

$$P\left(|U_{i\Delta}| \leq cv_{L,\alpha_L}\right) \sim 1 - 2\Phi\left(-\sqrt{2\log L}\right) \to 1,$$

as $\Delta \to 0$, where Φ is the cumulative distribution function of the standard normal distribution, given that $U_{i\Delta}$ converges to the standard normal distribution under the null.

Remark 3.2 *Following directly from Remark 3.1, we have the consistency of the aggregated jump dummy* $\hat{I}_{i\Delta}^* = \mathbf{1}\left(|U_{i\Delta}| > cv_{L,\alpha_L}\right)$ *and the individual jump dummy* $\hat{I}_{i\Delta}^k$*, i.e.,*

$$\hat{I}_{i\Delta}^* - I_{i\Delta}^* = o_p\left(1\right) \ \ and \ \hat{I}_{i\Delta}^k - I_{i\Delta}^k = o_p\left(1\right)$$

as $\Delta \to 0$*. Consequently, the estimated number of jumps* $\hat{K}$ *and their locations* $\hat{\tau}_k$ *are consistently estimated, i.e.,*

$$\hat{K} = \sum_{i=1}^{T} \hat{I}_{i\Delta}^* \to K \ \ and \ \hat{\tau}_k = \arg\max_i \left\{\hat{I}_{i\Delta}^k\right\} \to \tau_k.$$

As in Andersen et al. (2007b), Boudt et al. (2011), and Laurent and Shi (2020b), we also take the intraday periodicity in the volatility into consideration. The jump test statistic is

$$U_{i\Delta}^* = \frac{U_{i\Delta}}{\hat{f}_{i\Delta}^*},$$

where $\hat{f}_{i\Delta}^*$ is a robust-to-jumps estimate of the intraday periodicity. In the empirical application, we assume $\hat{f}_{i\Delta}^*$ to be the same across weeks but to vary within the week. The periodic component is obtained from the weighted standard deviation estimator of Boudt et al. (2011) but computed on the centered log returns $r_{i\Delta}^*$ rather than $r_{i\Delta}$ as in Laurent and Shi (2020b). See Boudt et al. (2011) and Laurent and Shi (2020b) for a detailed presentation of this estimator. In the simulation studies, for simplicity, we assume $\hat{f}_{i\Delta}^*$ to be the same across days and set the estimated intraday periodicity to the true value plus zero mean noise. This is because for the estimation of intraday periodicity, one would need a long sample period. However, it is very computationally intensive to simulate long time spans at the one-second frequency. Therefore, the estimated intraday periodicity $\hat{f}_{i\Delta}^*$ is assumed to follow a $\mathcal{N}(f_{i\Delta}^*, 0.01)$ distribution[11] and drawn from this distribution to account for estimation error of the periodicity on the jump test in our simulation study.

---

[11]For the variance of $\hat{f}_{i\Delta}$ (i.e., the setting of 0.01), we first estimated the intraday periodicity with the 10-minute Nasdaq log prices in 1996 using the parametric approach proposed by Andersen and Bollerslev (1998b). Using the estimated parameters, we simulate data and run a Monte Carlo study to obtain the mean squared error of the fitted intraday periodicity.

3.2.2 Feasible DF^J Test

The second step is to conduct the $DF^{\hat{J}}$ test based on the jump identification results. To do so, we replace K and $I_{i\Delta}^k$ in the regression model with their estimates such that

$$
y_{i\Delta} = \alpha + \sum_{k=1}^{\hat{K}} \phi_k \hat{I}_{i\Delta}^k + \beta y_{(i-1)\Delta} + v_{i\Delta}. \tag{21}
$$

The feasible test statistic $DF^{\hat{J}}$ is

$$
DF^{\hat{J}} = \left(\ddot{\beta} - 1 \right) \left[\frac{T \sum_{j=1}^T y_{(j-1)\Delta}^2 - \left(\sum_{j=1}^T y_{(j-1)\Delta} \right)^2}{\sum_{j=1}^T \left(y_{j\Delta} - \ddot{\beta} y_{(j-1)\Delta} - \ddot{\alpha} - \sum_{k=1}^{\hat{K}} \ddot{\phi}_k \hat{I}_{j\Delta}^k \right)^2} \right]^{1/2},
$$

where $\ddot{\alpha}$, $\ddot{\beta}$, and $\ddot{\phi}_k$ are the estimated OLS coefficients from regression (21). Let

$$
\ddot{\sigma}_v^2 = \sum_{i=1}^T \left(y_{i\Delta} - \ddot{\beta} y_{(i-1)\Delta} - \ddot{\alpha} - \sum_{k=1}^K \ddot{\phi}_k I_{i\Delta}^k \right)^2.
$$

Theorem 3.5 *The OLS estimators of regression* (21) *and the test statistic $DF^{\hat{J}}$ have the following limiting properties: as $\Delta \to 0$ (with N fixed),*

$$
T^{1/2} \left(\ddot{\phi}_k - \phi_k \right) \Longrightarrow \mathcal{N}(0, \sigma^2 N) \ and \ \ddot{\sigma}_v^2 \to \sigma^2 N
$$

under both the null and the alternative hypotheses; the feasible unit root test statistic

$$
DF^{\hat{J}} \Longrightarrow \frac{-\tilde{\Psi}_2 w_1 + \tilde{\Psi}_4}{\left(\tilde{\Psi}_3 - \tilde{\Psi}_2^2 \right)^{1/2}} \equiv \Upsilon_2 \tag{22}
$$

under the null hypothesis (11), and

$$
DF^{\hat{J}} \Longrightarrow \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1}{\left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2 \right)^{1/2}} + c \left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2 \right)^{1/2} \equiv \Upsilon_2^A \tag{23}
$$

under the alternative hypothesis (10).

Due to the asymptotic consistency of the jump identification procedure (Remark 3.2), the limiting distributions of the $DF^{\hat{J}}$ test are identical to those of DF^J.

Remark 3.3 *A feasible version of the $DF(J)$ test, denoted by $DF(\hat{J})$, employs the same test statistic (i.e., DF) and has the same limiting distributions (i.e., Υ_3 under the null and Υ_3^A under the alternative) as $DF(J)$. Unlike the $DF(J)$ test, it further replaces the jump related parameters in the limiting distributions with the*

estimated ones. We refer to the estimated limiting distributions as $\hat{\Upsilon}_3$ and $\hat{\Upsilon}_3^A$. The asymptotic equivalence of the original distributions and the estimated ones is ensured by the consistent properties of the jump test.

4 Simulation Studies

This section investigates the finite sample performance of the unit root test. We first consider a simple data generating process (DGP) with constant volatility (with or without jumps). We then extend this model with GARCH effects, intraday periodicity in the volatility and microstructure noise.

In practice, the true data generating process is unknown. When investigating the dynamic of the data series, one first needs to specify the null and the alternative hypothesis. While the null hypothesis is unit root, the alternative is either mean-reversion or explosiveness for a one-sided test. In other words, one needs to decide whether to conduct a left-sided or a right-sided test. This is, unfortunately, not immediately clear in most cases, especially when the dynamic of the data series is close to unity. One could decide to conduct a two-sided test but the information provided by a two-sided test might not be sufficient for some purposes (e.g., designing trading strategies). Alternatively, one could implement both the left- and right-sided tests as in our empirical application. It is, therefore, important to investigate the performance of the tests under all of the six scenarios listed in Table 1.

Table 1: Possible scenarios

DGP / Test	Left-sided test	Right-sided test
Unit root	Case 1	Case 2
Mean-reversion	Case 3	Case 4
Explosiveness	Case 5	Case 6

The first two cases are for studying the size of the tests, while Cases 3 and 6 allow us to investigate the power of the left- and right-sided tests. Finally, Cases 4 and 5 examine the possibility of false rejections when the alternative hypothesis is on the opposite side of the true DGP. The settings in Case 4 and 5 are unconventional but essential here due to the non-monotonicity of the limiting distributions (Figures 1, 3, and 5).

4.1 Constant Volatility

The data generating process is (11) under the null and (10) with $\theta \neq 0$ (or $\alpha \neq 1$) under the alternative. The value of θ is set to $\{-0.006, -0.004, -0.002\}$ under the mean reversion alternative and $\{0.002, 0.004, 0.006\}$ in the case of explosiveness. We consider the same parameter values for $y_0, N, \theta,$ and σ as in Section 2.3 and $\varepsilon_{i\Delta} \overset{i.i.d}{\sim} \mathcal{N}(0,1)$. In the case of jumps, the locations of jumps $\tau_{i\Delta}^k$ are drawn randomly from a uniform distribution. The number of jumps is set to one per week. The magnitude of jumps ϕ_k is set to $\kappa\sigma$ with $\kappa = 2$ for positive jumps and $\kappa = -2$ for negative jumps.

Each day of simulated log prices consists of 23,400 observations, corresponding to one-second data over

6.5 hours. The one-second log prices are then aggregated to obtain data at the 10-minute frequency.[12] The nominal size of the tests is 5%, and the number of replications is $1,000$. We compare the performance of the new test statistics $DF^{\hat{J}}$ and $DF(\hat{J})$ with the conventional unit root test DF. Jump dummies are constructed by employing the test statistic of Laurent and Shi (2020b) as presented in Section 3.2.1.

The empirical size and power of both the left-sided (i.e., $H_1 : \theta < 0$) and the right-sided (i.e., $H_1 : \theta > 0$) tests are reported in Table 2. The left panel is for the test against the mean reversion alternative, while the right panel is for the test against explosiveness. The top panel reports the unit root test results in the absence of jumps in log prices. The performance of the three tests is almost identical in this setting, which is as expected and reassuring of good performance (low false identification rate) for the jump detection procedure. The empirical sizes of both tests are close to the nominal size. The power of each test increases as the process deviates further from the random walk. Note that when $N = 60$ and $\theta = -0.002$, the power of the three left-sided tests is lower than the nominal size. The power of the left-sided tests, however, increases as θ deviates further from zero (in the negative direction). This result is consistent with our observation from Figures 1, 3, and 5. That is, as θ decreases from 0 to negative values, the distribution of the test statistic first moves to the right of the null distribution before turning to the left. Moreover, the power of the tests increases with the time span N. Notably, when $\theta = -0.002$, the power of the left-sided tests increases from 0.6% to approximately 25% as the time span extends from one quarter ($N = 60$) to approximately one year ($N = 200$).

The middle and bottom panels are for the cases with positive and negative jumps, respectively. One can see that in the presence of jumps (either positive or negative), the left-sided DF test is undersized (due to overlooked jumps), while the right-sided DF test, for the same reason, is severely oversized. The model under the null hypothesis (11) is equivalent to a random walk process with breaks in the drift (due to the presence of jumps).[13] The results of the left-sided test echo the literature documenting observational equivalences between unit roots and structural breaks (e.g., Perron, 1990; Banerjee et al., 1992; Perron, 1997; Lumsdaine and Papell, 1997). Our result for the right-sided test is consistent with the findings of Phillips and Shi (2019), where a random drift martingale process is considered. Although one could visually separate negative jumps from an upward expanding explosive process (Phillips and Shi, 2019), there is no solution in the literature for distinguishing positive jumps from upward explosive processes.

By including jump dummies in the model specifications, the $DF^{\hat{J}}$ test is able to isolate the impact of jumps while detecting breaks in the autoregressive coefficient. Both the $DF^{\hat{J}}$ and $DF(\hat{J})$ tests have reasonable sizes in all configurations. The size distortion of the DF tests translates into a lack of power for the left-sided DF test and more rejections for the right-sided DF test than the right-sided $DF^{\hat{J}}$ and $DF(\hat{J})$ tests. Interestingly, despite the low (absolute) values of the θ parameters considered in the simulation, $DF^{\hat{J}}$ and $DF(\hat{J})$ have

---

[12]The simulation results are qualitatively the same for 5-minute and 30-minute data and are therefore not reported to save space.

[13]This feature distinguishes jumps from bubbles, which are often modeled as a mildly explosive process (Phillips et al., 2011, 2015a; Phillips and Shi, 2018). The autoregressive coefficient of the mildly explosive process is greater than unity and takes the form of $\rho_T = 1 + cT^{-\alpha}$, with c being a constant, T being the sample size and $\alpha \in (0, 1)$.

Table 2: Empirical sizes and powers of the unit root tests at the 10-minute frequency: constant volatility. The nominal size is 5%.

θ	$H_1 : \alpha < 1$				$H_1 : \alpha > 1$			
	-0.006	-0.004	-0.002	0	0	0.002	0.004	0.006
No jumps								
$N = 60$								
DF	60.4	7.7	0.6	6.1	4.1	61.9	97.4	100.0
$DF^{\hat{J}}$	60.3	7.7	0.6	6.1	4.0	61.8	97.4	100.0
$DF(\hat{J})$	60.4	7.7	0.6	6.1	4.1	61.9	97.4	100.0
$N = 100$								
DF	100.0	53.8	3.5	5.4	5.2	83.6	100.0	100.0
$DF^{\hat{J}}$	100.0	53.8	3.5	5.4	5.2	83.6	100.0	100.0
$DF(\hat{J})$	100.0	53.8	3.5	5.4	5.1	83.6	100.0	100.0
$N = 200$								
DF	100.0	100.0	24.6	5.7	5.4	99.9	100.0	100.0
$DF^{\hat{J}}$	100.0	100.0	24.7	5.7	5.4	99.9	100.0	100.0
$DF(\hat{J})$	100.0	100.0	24.6	5.7	5.4	99.9	100.0	100.0
Positive jumps								
$N = 60$								
DF	23.5	3.7	0.5	1.5	20.6	61.7	94.2	100.0
$DF^{\hat{J}}$	74.6	18.1	3.0	4.6	4.1	26.8	83.6	100.0
$DF(\hat{J})$	53.6	23.7	12.3	4.9	3.5	40.8	92.8	100.0
$N = 100$								
DF	89.3	18.8	1.6	1.2	28.6	81.1	100.0	100.0
$DF^{\hat{J}}$	100.0	69.1	9.0	5.3	4.3	48.5	100.0	100.0
$DF(\hat{J})$	92.9	54.2	22.1	5.7	4.5	59.4	100.0	100.0
$N = 200$								
DF	100.0	97.1	6.7	0.6	33.9	100.0	100.0	100.0
$DF^{\hat{J}}$	100.0	100.0	37.7	4.7	5.2	99.3	100.0	100.0
$DF(\hat{J})$	100.0	97.8	39.2	5.3	5.4	99.7	100.0	100.0
Negative jumps								
$N = 60$								
DF	37.6	6.7	0.8	1.5	22.9	50.5	87.3	99.9
$DF^{\hat{J}}$	87.7	29.6	4.0	3.8	5.4	16.7	68.3	99.9
$DF(\hat{J})$	74.4	17.5	2.0	3.2	5.6	37.3	68.4	95.7
$N = 100$								
DF	98.2	36.7	2.0	1.1	30.0	66.0	99.9	100.0
$DF^{\hat{J}}$	100.0	89.4	16.1	4.1	5.9	27.9	99.2	100.0
$DF(\hat{J})$	100.0	82.2	10.8	4.8	5.4	44.6	91.5	100.0
$N = 200$								
DF	100.0	100.0	22.3	1.0	39.7	95.2	100.0	100.0
$DF^{\hat{J}}$	100.0	100.0	74.8	5.4	5.2	80.3	100.0	100.0
$DF(\hat{J})$	100.0	100.0	68.1	5.2	5.4	67.4	100.0	100.0

good power against both alternatives. As expected, the powers increase with $|\theta|$ and N. Between DF^J and $DF(J)$, none of the tests uniformly dominates the other in terms of sizes and powers.

Table 3 reports the rejection frequencies of the left-sided tests when the true process is explosive (Case 5) and the probabilities of rejecting the null hypothesis against explosiveness (right-sided tests) when the

true DGP is mean-reverting (Case 4). Recall that Figures 1, 3, and 5 show that when θ is negative and close to zero (mean-reversion), the right-sided test of all three methods (i.e., DF, DF^J, and $DF(J)$) have a non-negligible probability of making a false positive rejection (against the explosive alternative) in the limit. The simulation results in Table 3 are consistent with our theoretical results. In the absence of jumps, there are no obvious differences between the three approaches. While the left-sided tests are well-behaved (i.e., have close-to-zero probabilities of false rejection), the right-sided tests have substantial false rejection probabilities when the true DGP is mean-reverting (with small absolute values of θ and N). The problem of false rejection disappears when N increases to 200.

The story is different for cases with jumps. In the presence of jumps, the relative performance of DF^J and $DF(J)$ varies. Under the explosive DGP with jumps, the probability of falsely rejecting the unit root null against a mean-reverting alternative is generally very low for all three approaches. Nevertheless, the performance of DF^J is more stable than $DF(J)$ under this setting. As we can see, the false rejection probability of $DF(J)$ rises to around 8% when the jumps are negative, $\theta = 0.002$, and $N = \{60, 100\}$, while that of DF^J is close to zero under all parameter settings. Furthermore, Figure 6 shows that in the presence of jumps, the false identification issue of the right-sided tests is less severe for DF^J than DF and $DF(J)$. The simulation results in Table 3 are again consistent with our theoretical findings. In the presence of jumps, $DF^{\hat{J}}$ rejects the null hypothesis in favor of the wrong hypothesis much less frequently. For example, when $N = 60$, $\theta = -0.002$, and with positive jumps, the false rejection frequency of the right-sided DF^J test is 6.5%, compared to 34.4% for DF and 27.9% for $DF(J)$.

In finite samples, the number of jumps might be over- or under-estimated. The results reported in Table 3 have already accounted for the fact that the detection of jumps is subject to errors as the jump dummies are created based on the outcome of the intraday test for jumps. To further investigate the sensitivity of $DF^{\hat{J}}$ and $DF(\hat{J})$ to spurious jumps (i.e., when $\hat{K} > K$), we run another set of simulations. The design of the simulations is similar to the one in Table 3, but we added 5, 8, and 16 spuriously identified jumps to the regression model, respectively, for $N = 60, 100$ and 200. The locations of the spurious jumps are set randomly. Results are qualitatively the same (not reported for brevity), confirming that over-identification of jumps is not a big issue in finite samples. The under-identification of jumps (i.e., $\hat{K} < K$) is most likely to happen when jump sizes are small, as the power of the jump test is higher when the jump size is larger (Laurent and Shi, 2020b). The finite sample impact of the under-identification of jumps on the unit root test statistics is, therefore, expected to be marginal.

Table 3: The false rejection probabilities of the unit root tests under Case 4 and Case 5 at the 10-minute frequency: constant volatility. The nominal size is 5%.

	Case 5: $H_1 : \alpha < 1$			Case 4: $H_1 : \alpha > 1$		
	0.002	0.004	0.006	-0.006	-0.004	-0.002
			No jumps			
$N = 60$						
DF	0.1	0.0	0.0	0.2	6.9	32.8
$DF^{\hat{J}}$	0.1	0.0	0.0	0.2	6.9	32.9
$DF(\hat{J})$	0.1	0.0	0.0	0.2	6.9	32.9
$N = 100$						
DF	0.0	0.0	0.0	0.0	0.2	19.8
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.2	19.8
$DF(\hat{J})$	0.0	0.0	0.0	0.0	0.2	19.8
$N = 200$						
DF	0.0	0.0	0.0	0.0	0.0	1.3
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.0	1.3
$DF(\hat{J})$	0.0	0.0	0.0	0.0	0.0	1.3
			Positive jumps			
$N = 60$						
DF	0.0	0.0	0.0	1.9	15.9	34.4
$DF^{\hat{J}}$	0.2	0.0	0.0	0.0	0.6	6.5
$DF(\hat{J})$	0.2	0.0	0.0	3.8	15.9	27.9
$N = 100$						
DF	0.0	0.0	0.0	0.0	3.7	26.2
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.0	2.6
$DF(\hat{J})$	0.0	0.0	0.0	0.1	5.6	19.9
$N = 200$						
DF	0.0	0.0	0.0	0.0	0.0	8.9
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.0	0.0
$DF(\hat{J})$	0.0	0.0	0.0	0.0	0.0	7.3
			Negative jumps			
$N = 60$						
DF	0.2	0.0	0.0	0.8	10.5	31.8
$DF^{\hat{J}}$	0.8	0.0	0.0	0.0	0.2	5.0
$DF(\hat{J})$	8.5	1.4	0.0	0.0	0.9	10.9
$N = 100$						
DF	0.0	0.0	0.0	0.0	0.7	20.3
$DF^{\hat{J}}$	0.9	0.0	0.0	0.0	0.0	1.6
$DF(\hat{J})$	7.6	0.1	0.0	0.0	0.0	2.3
$N = 200$						
DF	0.0	0.0	0.0	0.0	0.0	2.4
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.0	0.0
$DF(\hat{J})$	1.5	0.0	0.0	0.0	0.0	0.0

4.2 Time-varying Volatility and Microstructure Noise

To study the impact of time-varying volatility and microstructure noise, we consider more general model specifications. Under the null hypothesis, efficient log prices are now generated as follows:

$$y_{i\Delta} = \alpha_0 + \sum_{k=1}^{K} \phi_k I_{i\Delta}^k + y_{(i-1)\Delta} + \lambda_{i\Delta}\varepsilon_{i\Delta}, \tag{24}$$

27

where the volatility of log returns consists of a deterministic term $f_{i\Delta}$ and a stochastic component $\sigma_{i\Delta}$ such that

$$\lambda_{i\Delta} = f_{i\Delta}\sigma_{i\Delta}\sqrt{\Delta}.$$

We assume that f varies within the day but for simplicity restrict it to be the same across the N days in this simulation. To simulate a realistic periodic factor, we follow Laurent and Shi (2020b) and take the estimated periodicity obtained using the parametric method proposed by Andersen and Bollerslev (1998b) on the 10-minute Nasdaq stock price index from January 2, 1996, to December 8, 2017. The periodic component $f_{i\Delta}$ used in the simulations is plotted in Figure 7. It displays the usual diurnal pattern found in the volatility of intraday returns of most individual stocks and stock indices. The value of $f_{i\Delta}$ ranges from 0.6 to 1.6.

Figure 7: The simulated 1-second periodicity $f_{i\Delta}$ illustrated for one day.
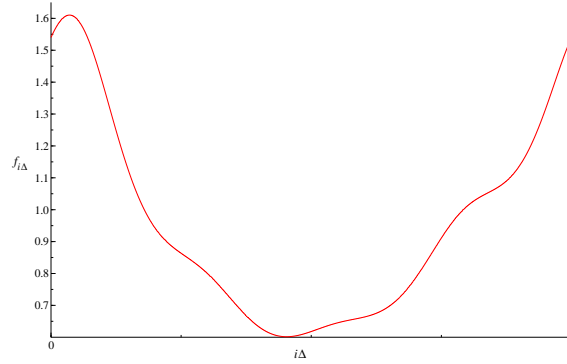
The stochastic component is assumed to follow the GARCH(1,1) diffusion process of Nelson (1991), which has a discretized form of

$$\sigma_{i\Delta}^2 = \delta_0 + \sigma_{(i-1)\Delta}^2(\beta_1 + \alpha_1\varepsilon_{i\Delta}), \tag{25}$$

where $\delta_0 = \kappa\omega\Delta$, $\beta_1 = 1 - \kappa\Delta$, $\alpha_1 = \sqrt{2\lambda\kappa\Delta}$, and $\varepsilon_{i\Delta} \overset{i.i.d}{\sim} \mathcal{N}(0,1)$. As in Andersen and Bollerslev (1998), we choose the parameters $\kappa = 0.035$ and $\lambda = 0.296$ to simulate a log price process with realistic GARCH effects and set $\omega = 0.01^2$ such that $E(\sigma_{i\Delta}^2) = 0.01^2$ as in the previous simulations.

Under the alternative, we have

$$y_{i\Delta} = \alpha_0 + \sum_{k=1}^{K}\phi_k I_{i\Delta}^k + \beta_0 y_{(i-1)\Delta} + \lambda_{i\Delta}\varepsilon_{i\Delta}. \tag{26}$$

The settings of α_0, β_0 and jumps are the same as in the previous section.

Additionally, we assume that log prices are contaminated by microstructure noise such that $y_{i\Delta}^*$ is observed instead of the true efficient log price $y_{i\Delta}$, where

$$y_{i\Delta}^* = y_{i\Delta} + \varpi v_{i\Delta}$$

with $\varpi^2 = \xi\sqrt{\frac{1}{\Delta}\sum_{j=1}^{1/\Delta}\sigma_{i\Delta}^4}$ and $v_{i\Delta} \overset{i.i.d}{\sim} \mathcal{N}(0,1)$. We set ξ to 0.0005.

Table 4: Empirical sizes and powers of the unit root tests at the 10-minute frequency: GARCH effects, intraday periodicity and microstructure noise. The nominal size is 5%.

θ	$H_1 : \alpha < 1$				$H_1 : \alpha > 1$			
	-0.006	-0.004	-0.002	0	0	0.002	0.004	0.006
	No jumps							
$N = 60$								
DF	57.0	8.1	0.9	7.3	5.1	64.1	96.0	100.0
$DF^{\hat{J}}$	57.3	8.1	0.9	7.4	5.2	64.1	96.0	100.0
$DF(\hat{J})$	57.4	8.1	0.9	7.4	5.2	64.1	96.0	100.0
$N = 100$								
DF	98.9	48.2	2.4	6.6	5.3	82.1	100.0	100.0
$DF^{\hat{J}}$	98.9	48.0	2.4	6.7	5.2	82.1	100.0	100.0
$DF(\hat{J})$	98.9	48.0	2.4	6.7	5.3	82.2	100.0	100.0
$N = 200$								
DF	100.0	99.6	19.6	6.0	5.6	99.6	100.0	100.0
$DF^{\hat{J}}$	100.0	99.7	19.3	5.7	5.5	99.6	100.0	100.0
$DF(\hat{J})$	100.0	99.7	19.5	5.7	5.5	99.6	100.0	100.0
	Positive jumps							
$N = 60$								
DF	24.3	3.5	0.7	1.7	22.8	63.0	93.0	100.0
$DF^{\hat{J}}$	67.9	16.3	3.6	5.3	5.4	29.4	81.6	99.9
$DF(\hat{J})$	50.7	24.2	14.6	5.0	5.6	43.9	90.1	100.0
$N = 100$								
DF	24.3	3.5	0.7	1.7	22.8	63.0	93.0	100.0
$DF^{\hat{J}}$	67.9	16.3	3.6	5.3	5.4	29.4	81.6	99.9
$DF(\hat{J})$	50.7	24.2	14.6	5.0	5.6	43.9	90.1	100.0
$N = 200$								
DF	100.0	88.3	6.4	0.9	35.9	99.7	100.0	100.0
$DF^{\hat{J}}$	100.0	99.6	30.9	4.8	5.5	97.8	100.0	100.0
$DF(\hat{J})$	100.0	94.1	39.7	4.9	5.6	98.3	100.0	100.0
	Negative jumps							
$N = 60$								
DF	38.7	6.1	0.8	1.4	23.2	52.0	85.4	99.6
$DF^{\hat{J}}$	80.4	27.7	4.9	5.2	7.1	17.7	67.6	98.9
$DF(\hat{J})$	68.2	16.3	2.5	5.2	6.6	38.9	67.6	93.2
$N = 100$								
DF	93.3	32.8	2.6	1.9	30.2	63.2	98.8	100.0
$DF^{\hat{J}}$	99.9	84.3	13.4	5.4	4.1	25.9	98.2	100.0
$DF(\hat{J})$	99.7	74.0	8.9	4.9	4.5	42.2	88.4	99.9
$N = 200$								
DF	100.0	97.3	15.8	1.0	37.6	89.7	100.0	100.0
$DF^{\hat{J}}$	100.0	100.0	65.0	5.1	5.7	71.4	100.0	100.0
$DF(\hat{J})$	100.0	100.0	59.9	5.2	5.9	64.2	100.0	100.0

Table 4 displays the sizes and powers of the one-sided tests in the presence of microstructure noise, GARCH effects and intraday periodicity for a nominal size of 5%. The organization of the table is identical to that of Table 2. Table 5 corresponds to Table 3 presenting results for Case 4 and 5 but with time-varying

Table 5: The false rejection probabilities under Case 4 and Case 5 at the 10-minute frequency: GARCH effects, intraday periodicity and microstructure noise. The nominal size is 5%.

	Case 5: $H_1 : \alpha < 1$			Case 4: $H_1 : \alpha > 1$		
	0.002	0.004	0.006	-0.006	-0.004	-0.002
			No jumps			
$N = 60$						
DF	0.1	0.0	0.0	0.4	7.8	31.6
$DF^{\hat{J}}$	0.1	0.0	0.0	0.4	7.7	31.5
$DF(\hat{J})$	0.1	0.0	0.0	0.4	7.8	31.5
$N = 100$						
DF	0.0	0.0	0.0	0.0	0.4	20.2
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.4	20.5
$DF(\hat{J})$	0.0	0.0	0.0	0.0	0.4	20.4
$N = 200$						
DF	0.0	0.0	0.0	0.0	0.0	3.2
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.0	3.2
$DF(\hat{J})$	0.0	0.0	0.0	0.0	0.0	3.2
			Positive jumps			
$N = 60$						
DF	0.1	0.0	0.0	2.1	14.9	32.0
$DF^{\hat{J}}$	0.6	0.0	0.0	0.0	1.2	7.0
$DF(\hat{J})$	0.2	0.0	0.0	4.1	16.2	26.3
$N = 100$						
DF	0.0	0.0	0.0	0.0	3.4	26.8
$DF^{\hat{J}}$	0.1	0.0	0.0	0.0	0.0	2.8
$DF(\hat{J})$	0.0	0.0	0.0	0.0	4.9	19.6
$N = 200$						
DF	0.0	0.0	0.0	0.0	0.0	12.7
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.0	0.2
$DF(\hat{J})$	0.0	0.0	0.0	0.0	0.2	9.0
			Negative jumps			
$N = 60$						
DF	0.0	0.0	0.0	0.9	12.2	32.9
$DF^{\hat{J}}$	1.1	0.0	0.0	0.0	0.8	7.3
$DF(\hat{J})$	8.8	1.8	0.0	0.0	1.6	12.3
$N = 100$						
DF	0.0	0.0	0.0	0.1	1.6	21.4
$DF^{\hat{J}}$	0.3	0.0	0.0	0.0	0.0	1.0
$DF(\hat{J})$	9.1	0.4	0.1	0.0	0.0	2.1
$N = 200$						
DF	0.0	0.0	0.0	0.0	0.0	5.2
$DF^{\hat{J}}$	0.0	0.0	0.0	0.0	0.0	0.0
$DF(\hat{J})$	4.2	0.0	0.0	0.0	0.0	0.0

volatilities. The results are qualitatively the same as in the case of constant volatility, which suggests that heteroskedasticity and microstructure noise have little impact on the performance of the unit root tests when they are applied to 10-minute data and when $N \geq 60$.[14]

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[14]Unreported simulation results suggest that time-varying volatility has a larger impact on test performance when the window size is small, e.g., when $N < 5$. In this case, as in Boswijk and Zu (2018), an adaptive wild bootstrap version of our test can be

The simulation results can be summarized as follows. There are no visible differences among the three methods (DF, $DF^{\hat{J}}$, $DF(\hat{J})$) in the absence of jumps. The relative performance of the three methods in the presence of jumps are detailed below.

Case 1 and 2 (sizes) In the presence of jumps, the left-sided DF test is undersized while the right-sided DF test is significantly oversized. On the contrary, both $DF^{\hat{J}}$ and $DF(\hat{J})$ have satisfactory sizes.

Case 3 (power of the left-sided tests) While both $DF^{\hat{J}}$ and $DF(\hat{J})$ outperform DF, the relative performance of $DF^{\hat{J}}$ and $DF(\hat{J})$ depends on the parameter settings. The power of the $DF^{\hat{J}}$ test is larger than that of the $DF(\hat{J})$ test when there are negative jumps in the sample. When jumps are positive, the $DF(\hat{J})$ test has higher power than the $DF^{\hat{J}}$ test when θ is close to zeros (i.e., $\theta = -0.002$) but lower power when θ moves further away from zero (e.g., $\theta = -0.006$).

Case 4 (probability of false rejections: mean-reverting DGPs and the right-sided tests) When the true DGP is mean-reverting, there is a substantially higher chance of false rejection with the right-sided $DF(\hat{J})$ test than the right-sided $DF^{\hat{J}}$ test. This is especially when N is small and the dynamic of the data series is close to the unit root. The false rejection probability can be as high as 27.9% for the $DF(\hat{J})$ test but less than 7.3% for the $DF^{\hat{J}}$ test.

Case 5 (probability of false rejections: explosive DGPs and the left-sided tests) When the true DGP is explosive, the three approaches generally do not falsely reject the null of unit root against a mean-reverting alternative. In the presence of negative jumps, however, unlike the $DF^{\hat{J}}$ test, the $DF(\hat{J})$ test has a high false rejection probability when θ is closer to zero (e.g., about 8% when $N = 60, 100$ and $\theta = 0.002$).

Case 6 (power of the right-sided tests) The power of $DF(\hat{J})$ is higher than $DF^{\hat{J}}$ when $N \leq 100$ but lower when the jumps are negative and $N = 200$.

Although the $DF(\hat{J})$ test has higher power under some parameter settings, the DF^{J} test has a substantially lower probability in rejecting the unit root null against the explosive alternative when the true DGP is mean-reverting and has jumps. For this reason, and since there is abundant evidence on the presence of jumps in high-frequency asset prices, we use the $DF^{\hat{J}}$ test in empirical applications.
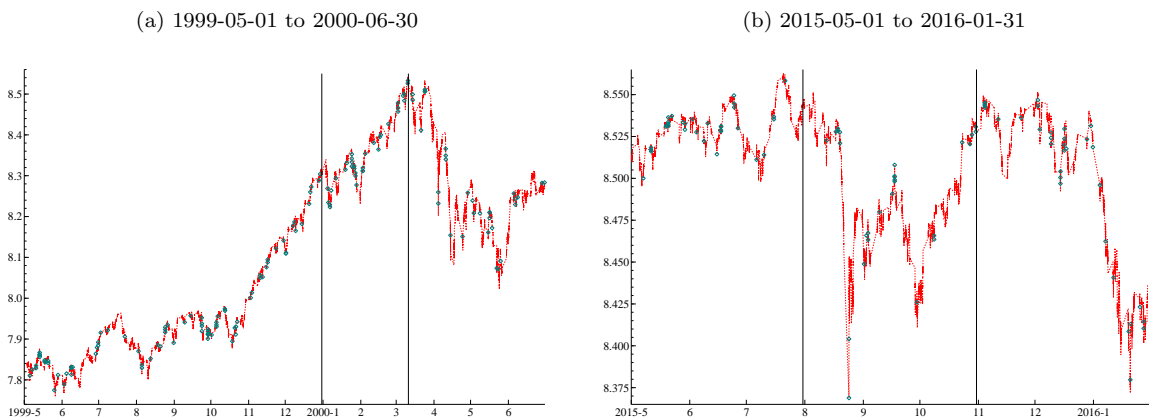
5   Empirical Application

The primary purpose of this section is to show the impact of jumps on unit root testing on intraday data by comparing the performance of the standard DF test and the proposed $DF^{\hat{J}}$ test. The $DF(\hat{J})$ test is not considered because it has a much higher probability of rejecting against wrong hypotheses (as discussed). We investigate the dynamics of the 10-minute log prices of the Nasdaq composite index over two sample periods

employed. We leave this extension for further research.

(1999-05-01 to 2000-06-30 and 2015-05-01 to 2016-01-31). The data are downloaded from Thomson Reuters DataScope and displayed in Figure 8.

The first period falls in the famous dot-com bubble period (Phillips et al., 2011; Shi and Song, 2016). It has been widely recognized that asset prices exhibit explosive dynamics in the presence of speculative bubbles (Diba and Grossman 1988; Phillips et al. 2011; Phillips et al. 2015a,b). Evidence of speculative bubbles has been detected in various markets with low-frequency data (daily, weekly or monthly).[15] The dot-com bubble is the most prominent episode. We can see a dramatic increase in the Nasdaq stock price in the second half of 1999. The market peaked on March 10, 2000, followed by a sharp downturn.

The second episode is around the 2015-2016 stock market sell-off, triggered by the bursting of the Chinese stock market bubble on 12 June 2015. We observe dramatic turbulence in the Nasdaq stock market between August and October. In particular, the Nasdaq market dropped 15.59% from 19 August to 24 August. It recovered to approximately the same level as before the crash by the end of October 2015. Various models have been proposed for capturing the dynamics of a bubble bursting and market crashes (e.g., a mildly stationary process of Phillips and Shi, 2018 and the random drift martingale process of Phillips and Shi, 2019) but yet to be tested empirically.

Figure 8: The 10-minute log prices of the Nasdaq composite index for two sample periods. The diamonds indicate the jumps used in the $DF^{\hat{J}}$ test. The vertical lines indicate the cutoff dates of each subsample.

(a) 1999-05-01 to 2000-06-30   (b) 2015-05-01 to 2016-01-31

We first apply the jump test of Laurent and Shi (2020b) (with the same critical values as in the simulation studies) to the two data series to create the jump dummies. In empirical applications on jump detection with high-frequency data, overnight returns are often removed because they convey information on a more extended period than the other returns (i.e., 17.5 hours rather than 10 minutes in our case). Removing the first observation of each day is obviously not a solution for unit root tests with log prices. Therefore, we keep the first observations of the days (and hence overnight returns) for both the jump and unit root tests. The variance of overnight returns can be captured by the periodicity component, which is taken care of in

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[15]See, for example, Phillips et al. (2011), Gutierrez (2012); Etienne et al. (2013), Pavlidis et al. (2016), Fantazzini (2016), Shi (2017) and Hu and Oxley (2018).

our test for jumps. Moreover, we show in our simulations that the periodicity of variances does not have a significant impact on unit root tests when N is larger than 60. Therefore, the inclusion of overnight returns is not expected to affect our test outcomes. The identified jumps are marked with diamonds in Figure 8. There are 149 jumps during the first sample (i.e., 1999-05-1 and 2000-06-30) and 91 during the second one (i.e., 2015-05-01 and 2016-01-31). It is clear from this figure that jumps are not rare events. Furthermore, some of the detected jumps are very large and therefore expected to have an impact on the DF test.

For the unit root tests, we divide each period into three subsamples, guided by the important events discussed above. The cutoff dates of the subsamples are marked by vertical lines in Figure 8. The unit root test statistics DF and $DF^{\hat{J}}$ and their corresponding asymptotic critical values for the left- and right-sided tests (5% and 95%) are reported in Table 6, along with the exact dates of each subsample and the number of jumps detected in each subsample.[16]

For the dot-com bubble period, both procedures detect explosive dynamics in the Nasdaq stock market in the first subsample (between May 1999 and December 1999).[17] In the second subsample, while the null hypothesis of a random walk is still rejected against explosiveness with the DF test, the DF^J test does not reject the null against the explosive alternative. The distinct outcomes of the DF and $DF^{\hat{J}}$ tests could potentially be explained by our findings in Sections 3 and 4. That is, jumps could lead to spurious rejections of the DF test against the alternative hypothesis of explosiveness. In contrast, the DF^J test, which accounts for the presence of jumps, has satisfactory performance under this circumstance. The $DF^{\hat{J}}$ test suggests that the process returns to a random walk in the period from 2000-01-01 to 2000-03-10 before reaching the peak of the bubble episode. This result has important implications for traders who have every intention to withdraw from the market before bubbles collapse. Interestingly, the two tests again agree when applied to the third subsample, spanning between 11 March 2000 and 30 June 2000. Indeed, we fail to reject the null hypothesis during this period using both tests, suggesting that the bursting of the dot-com bubble follows a random walk pattern.

Similarly, for the second sample period (2015-2016), DF and $DF^{\hat{J}}$ yield consistent results in the first and third subsamples but draw different conclusions in the second subsample. Both tests conclude that the log Nasdaq price follows a unit root process in the first and third subsamples. For the turbulent 2.5 months in 2015 (from 1 August to 15 October), the $DF^{\hat{J}}$ rejects the null against the mean reversion alternative, while the DF test fails to do so. Again, this finding is not surprising, as we find in Sections 3 and 4 that jumps decrease the power of the DF test against mean reversion, and we observe jumps with extremely large magnitudes over this period (e.g., at the opening of 24 August 2015). Interestingly, unlike the bursting of

---

[16]Since the jump dummies are orthogonal to each other and $\hat{\phi}_k$ is asymptotically normally distributed (according to Theorem 3.2), standard t-tests can be used to eliminate insignificant jump dummies in Equation (10). As the results are qualitatively the same when including all jump dummies or only dummies that are significant at the conventional significance levels, we only report the results with all jump dummies. Unreported simulations reveal similar sizes and powers for the $DF^{\hat{J}}$ test when the regression includes all jump dummies (including redundant ones) or only significant ones.

[17]The presence of explosive dynamics in asset prices does not imply the existence of bubbles. An additional necessary step is to control for the impact of market fundamentals. Stock market fundamentals are often proxied by dividends or earnings, which are unfortunately not available at such a high frequency. Therefore, we do not refer to the explosive dynamics as bubbles in this paper.

Table 6: Results of the DF and $DF^{\hat{J}}$ tests

Start	End	DF	left cv	right cv	$DF^{\hat{J}}$	left cv	right cv	Jumps
1999-05-01	1999-12-31	**1.639**	-2.857	-0.089	**2.215**	-2.819	0.062	84
2000-01-01	2000-03-10	**0.160**	-2.857	-0.089	0.312	-2.672	0.404	34
2000-03-11	2000-06-30	-2.008	-2.857	-0.089	-1.937	-2.809	0.005	31
2015-05-01	2015-07-31	-2.357	-2.857	-0.089	-2.426	-2.823	-0.038	32
2015-08-01	2015-10-15	-2.406	-2.857	-0.089	**-3.026**	-2.714	0.268	22
2015-10-16	2016-01-31	-0.788	-2.857	-0.089	-0.120	-2.746	0.057	37

Note: The statistics highlighted in bold are significant at the 5% level using either the left- or right-sided critical values. The figures in the columns left cv and right cv are the critical values used for the corresponding left-sided and right-sided tests, respectively. The figures in the last column correspond to the number of jumps detected using the test of Laurent and Shi (2020b).

the dot-com bubble, the $DF^{\hat{J}}$ test suggests that the stock market crash in late 2015 follows a mean reversion process.

Finally, although the availability of high-frequency data allows us to conduct the unit root tests using data over short time periods and hence reduce the probability of having structural breaks within the sample period, it does not completely rule out this possibility. The performance of the unit root tests in the presence of structural breaks remains unknown. One could potentially account for structural breaks with the model proposed by Jiang et al. (2020) but extended to allow for jumps. Here, we provide examples of cases when both DF and $DF^{\hat{J}}$ reject the unit root null hypothesis in favor of the same alternative and, more important, when they contradict, with carefully divided subsamples. A comprehensive analysis of the structural break issue and a more extensive empirical application over a longer sample period is left for future work.

6 Conclusion

This paper provides an efficient tool for detecting deviations of asset prices from a random walk with intraday high-frequency data. The proposed tool is based on unit root tests but takes the empirical features of high-frequency data (particularly jumps) into consideration. The null hypothesis is a random walk, while the alternative hypothesis is either mean reversion or explosiveness. Using in-fill asymptotics, we show that the conventional DF tests could lead to severe size distortions in the presence of jumps, according to both the asymptotic and simulation results.

We propose two new tests that account for the possible presence of jumps, denoted DF^{J} and $DF(J)$ for the infeasible version and $DF^{\hat{J}}$ and $DF(\hat{J})$ for the feasible one. The limiting distributions of the new test statistics under both the null and the alternative are provided. Both tests depend on nuisance parameters for which we propose consistent estimators. Importantly, we show that the feasible versions of the tests (i.e., relying on a test to identify jumps) have the same limiting properties as the infeasible ones (i.e., assuming true jump occurrences). Simulation results reveal the satisfactory performance (in terms of size and power) of the new tests but also that $DF(\hat{J})$ tends to reject too often against the wrong alternative when the process

is mildly mean-reverting ($\theta < 0$ but close to zero), and N is relatively small. Therefore, we recommend the use of $DF^{\hat{J}}$ for empirical applications.

Furthermore, we show via simulations that conditional heteroskedasticity, intraday periodicity, and microstructure noise do not affect the finite sample performance of the tests when the test window is applied to one quarter of the data (or more), and the sampling frequency is 10 minutes or lower.

We apply the conventional DF test and $DF^{\hat{J}}$ to the 10-minute log prices of the Nasdaq composite index around the peak of the dot-com bubble (1999-2000) and the 2015-2016 stock market sell-off periods. Both tests reject the null against the explosive alternative in late 1999. The two unit root tests, however, provide contradictory results in the early 2000s before the bursting of the dot-com bubble and in late 2015 when the market experienced turbulence. We attribute these differences to the lack of power of the left-sided DF test and the oversize issue of the right-sided DF test when jumps are ignored. The $DF^{\hat{J}}$ test suggests that log Nasdaq prices switch back to a random walk dynamic (from being explosive) as the peak of the bubble approaches. Additionally, the dot-com bubble collapses in a random walk fashion, while the 2015 stock market crash follows a mean-reverting process.

Appendix: Proofs

Asymptotics of the DF statistic

Proof of Theorem 2.1. The least square estimators of the standardized intercept and autoregressive coefficient are

$$
\begin{bmatrix} \hat{\alpha} \\ \hat{\beta} - 1 \end{bmatrix} = \sigma\sqrt{\Delta} \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix}^{-1} \begin{bmatrix} \sum \varepsilon_{j\Delta} \\ \sum y_{(j-1)\Delta}\varepsilon_{j\Delta} \end{bmatrix}.
$$

Let $\sum$ denotes summation over $j = 1, \cdots, T$. Based on Lemma 2.1(d), the appropriate scaling matrix is $\Upsilon_T = diag\left(\sqrt{T}, \sqrt{T}\right)$. Pre-multiplying the above equation by $T^{1/2}\Upsilon_T$ leads to

$$
\begin{aligned}
T^{1/2}\Upsilon_T \begin{bmatrix} \hat{\alpha} \\ \hat{\beta} - 1 \end{bmatrix} &= \begin{bmatrix} T\hat{\alpha} \\ T\left(\hat{\beta} - 1\right) \end{bmatrix} \\
&= \sigma N^{1/2} \left\{ \Upsilon_T^{-1} \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix} \Upsilon_T^{-1} \right\}^{-1} \left\{ \Upsilon_T^{-1} \begin{bmatrix} \sum \varepsilon_{j\Delta} \\ \sum y_{(j-1)\Delta}\varepsilon_{j\Delta} \end{bmatrix} \right\}.
\end{aligned}
$$

The first term

$$
\begin{aligned}
&\Upsilon_T^{-1} \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix} \Upsilon_T^{-1} \\
&= \begin{bmatrix} \sqrt{T} & 0 \\ 0 & \sqrt{T} \end{bmatrix}^{-1} \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix} \begin{bmatrix} \sqrt{T} & 0 \\ 0 & \sqrt{T} \end{bmatrix}^{-1}
\end{aligned}
$$

$$= \begin{bmatrix} 1 & T^{-1} \sum y_{(j-1)\Delta} \\ T^{-1} \sum y_{(j-1)\Delta} & T^{-1} \sum y_{(j-1)\Delta}^2 \end{bmatrix} \Longrightarrow \begin{bmatrix} 1 & \sigma N^{1/2} \Psi_2 \\ \sigma N^{1/2} \Psi_2 & \sigma^2 N \Psi_3 \end{bmatrix}.$$

The second term

$$\Upsilon_{T_n}^{-1} \begin{bmatrix} \sum \varepsilon_{j\Delta} \\ \sum y_{(j-1)\Delta} \varepsilon_{j\Delta} \end{bmatrix} = \begin{bmatrix} T^{-1/2} \sum \varepsilon_{j\Delta} \\ T^{-1/2} \sum y_{(j-1)\Delta} \varepsilon_{j\Delta} \end{bmatrix} \Longrightarrow \begin{bmatrix} w_1 \\ \sigma N^{1/2} \Psi_4 \end{bmatrix}.$$

Combining these two terms, we have

$$\begin{bmatrix} T\hat{\alpha} \\ T\left(\hat{\beta} - 1\right) \end{bmatrix} \Longrightarrow \sigma N^{1/2} \begin{bmatrix} 1 & \sigma N^{1/2} \Psi_2 \\ \sigma N^{1/2} \Psi_2 & \sigma^2 N \Psi_3 \end{bmatrix}^{-1} \begin{bmatrix} w_1 \\ \sigma N^{1/2} \Psi_4 \end{bmatrix}$$

$$= \frac{1}{\Psi_3 - \Psi_2^2} \begin{bmatrix} \sigma N^{1/2} \left(\Psi_3 w_1 - \Psi_2 \Psi_4\right) \\ -\Psi_2 w_1 + \Psi_4 \end{bmatrix}.$$

Furthermore,

$$\begin{aligned}
\hat{\sigma}_v^2 &= \sum \left(y_{j\Delta} - \hat{\alpha} - \hat{\beta} y_{(j-1)\Delta}\right)^2 \\
&= \sum \left[\sigma\sqrt{\Delta}\varepsilon_{j\Delta} - \left(\hat{\beta} - 1\right) y_{(j-1)\Delta} - \hat{\alpha}\right]^2 \\
&= \sum \left[\sigma^2 \Delta \varepsilon_{j\Delta}^2 + \left(\hat{\beta} - 1\right)^2 y_{(j-1)\Delta}^2 + \hat{\alpha}^2 - 2\sigma\sqrt{\Delta}\left(\hat{\beta} - 1\right) y_{(j-1)\Delta}\varepsilon_{j\Delta} - 2\sigma\sqrt{\Delta}\hat{\alpha}\varepsilon_{j\Delta} + 2\hat{\alpha}\left(\hat{\beta} - 1\right) y_{(j-1)\Delta}\right] \\
&= \sigma^2 N \left(\frac{1}{T}\sum \varepsilon_{j\Delta}^2\right) + T\left(\hat{\beta} - 1\right)^2 \left(\frac{1}{T}\sum y_{(j-1)\Delta}^2\right) + T\hat{\alpha}^2 - 2\sigma N^{1/2}\left(\hat{\beta} - 1\right)\left(T^{-1/2}\sum y_{(j-1)\Delta}\varepsilon_{j\Delta}\right) \\
&\quad - 2\sigma N^{1/2}\hat{\alpha}\left(T^{-1/2}\sum \varepsilon_{j\Delta}\right) + 2T\hat{\alpha}\left(\hat{\beta} - 1\right)\left(\frac{1}{T}\sum y_{(j-1)\Delta}\right) \\
&= \sigma^2 N \left(\frac{1}{T}\sum \varepsilon_{j\Delta}^2\right)[1 + o_p(1)] \to \sigma^2 N.
\end{aligned}$$

The DF statistics is

$$DF = \frac{\left(\hat{\beta} - 1\right)\left[T \sum_{j=1}^T y_{(j-1)\Delta}^2 - \left(\sum_{j=1}^T y_{(j-1)\Delta}\right)^2\right]^{1/2}}{\left[\sum_{j=1}^T \left(y_{j\Delta} - \hat{\alpha} - \hat{\beta} y_{(j-1)\Delta}\right)^2\right]^{1/2}} \Longrightarrow \frac{-\Psi_2 w_1 + \Psi_4}{\left(\Psi_3 - \Psi_2^2\right)^{1/2}}.$$

∎

Proof of Theorem 2.2. The least square estimators of the standardized intercept and the autoregressive coefficients are

$$\begin{bmatrix} \hat{\alpha} - \alpha_0 \\ \hat{\beta} - \beta_0 \end{bmatrix} = \sigma\sqrt{\Delta} \begin{bmatrix} T & \sum y_{(i-1)\Delta} \\ \sum y_{(i-1)\Delta} & \sum y_{(i-1)\Delta}^2 \end{bmatrix}^{-1} \begin{bmatrix} \sum \varepsilon_{i\Delta} \\ \sum y_{(i-1)\Delta} \varepsilon_{i\Delta} \end{bmatrix}.$$

Let $\sum$ denotes summation over $i = 1, \cdots, T$. Based on Lemma 2.2(d), the appropriate scaling matrix is $\Upsilon_T = diag\left(\sqrt{T}, \sqrt{T}\right)$. Pre-multiplying the above equation by $T^{1/2}\Upsilon_T$ leads to

$$T^{1/2}\Upsilon_T \begin{bmatrix} \hat{\alpha} - \alpha_0 \\ \hat{\beta} - \beta_0 \end{bmatrix} = \begin{bmatrix} T(\hat{\alpha} - \alpha_0) \\ T\left(\hat{\beta} - \beta_0\right) \end{bmatrix}$$

$$= \sigma N^{1/2} \left\{ \Upsilon_T^{-1} \begin{bmatrix} T & \sum y_{(i-1)\Delta} \\ \sum y_{(i-1)\Delta} & \sum y_{(i-1)\Delta}^2 \end{bmatrix} \Upsilon_T^{-1} \right\}^{-1} \left\{ \Upsilon_T^{-1} \begin{bmatrix} \sum \varepsilon_{i\Delta} \\ \sum y_{(i-1)\Delta}\varepsilon_{i\Delta} \end{bmatrix} \right\}.$$

The first term

$$\Upsilon_T^{-1} \begin{bmatrix} T & \sum y_{(i-1)\Delta} \\ \sum y_{(i-1)\Delta} & \sum y_{(i-1)\Delta}^2 \end{bmatrix} \Upsilon_T^{-1}$$

$$= \begin{bmatrix} 1 & T^{-1}\sum y_{(i-1)\Delta} \\ T^{-1}\sum y_{(i-1)\Delta} & T^{-1}\sum y_{(i-1)\Delta}^2 \end{bmatrix} \implies \begin{bmatrix} 1 & \sigma N^{1/2}\Xi_2 \\ \sigma N^{1/2}\Xi_2 & \sigma^2 N\Xi_3 \end{bmatrix}.$$

The second term

$$\Upsilon_T^{-1} \begin{bmatrix} \sum \varepsilon_{i\Delta} \\ \sum y_{(i-1)\Delta}\varepsilon_{i\Delta} \end{bmatrix} = \begin{bmatrix} T^{-1/2}\sum \varepsilon_i \\ T^{-1/2}\sum y_{(i-1)\Delta}\varepsilon_{i\Delta} \end{bmatrix} \implies \begin{bmatrix} w_1 \\ \sigma N^{1/2}\Xi_4 \end{bmatrix}.$$

Combining these two terms, we have

$$\begin{bmatrix} T(\hat{\alpha} - \alpha_0) \\ T\left(\hat{\beta} - \beta_0\right) \end{bmatrix} \implies \sigma N^{1/2} \begin{bmatrix} 1 & \sigma N^{1/2}\Xi_2 \\ \sigma N^{1/2}\Xi_2 & \sigma^2 N\Xi_3 \end{bmatrix}^{-1} \begin{bmatrix} w_1 \\ \sigma N^{1/2}\Xi_4 \end{bmatrix}$$

$$= \frac{1}{\Xi_3 - \Xi_2^2} \begin{bmatrix} \sigma N^{1/2}\left(\Xi_3 w_1 - \Xi_2\Xi_4\right) \\ -\Xi_2 w_1 + \Xi_4 \end{bmatrix}.$$

Therefore, $\hat{\beta} - \beta_0$ converges at rate T to the following quantity

$$T\left(\hat{\beta} - \beta_0\right) \implies \frac{-\Xi_2 w_1 + \Xi_4}{\Xi_3 - \Xi_2^2}.$$

Furthermore, as in the proof of Theorem 2.1, $\hat{\sigma}_v^2 = \sum \left(y_{j\Delta} - \hat{\alpha} - \hat{\beta}y_{(j-1)\Delta}\right)^2 \to \sigma^2 N$. The DF statistic is

$$\begin{aligned} DF &= \left(\hat{\beta} - 1\right) \left[\frac{T\sum_{i=1}^T y_{(i-1)\Delta}^2 - \left(\sum_{i=1}^T y_{(i-1)\Delta}\right)^2}{\sum_{i=1}^T \left(y_{i\Delta} - \hat{\alpha} - \hat{\beta}y_{(i-1)\Delta}\right)^2}\right]^{1/2} \\ &= \left(\hat{\beta} - \beta_0\right) \left[\frac{T\sum_{i=1}^T y_{(i-1)i\Delta}^2 - \left(\sum_{i=1}^T y_{(i-1)\Delta}\right)^2}{\sum_{i=1}^T \left(y_{i\Delta} - \hat{\alpha} - \hat{\beta}y_{(i-1)\Delta}\right)^2}\right]^{1/2} + \left(\beta_0 - 1\right)\left[\frac{T\sum_{i=1}^T y_{(i-1)\Delta}^2 - \left(\sum_{i=1}^T y_{(i-1)\Delta}\right)^2}{\sum_{i=1}^T \left(y_{i\Delta} - \hat{\alpha} - \hat{\beta}y_{(i-1)\Delta}\right)^2}\right]^{1/2} \end{aligned}$$

$$\implies \quad \frac{-\Xi_2 w_1 + \Xi_4}{\left(\Xi_3 - \Xi_2^2\right)^{1/2}} + c\left(\Xi_3 - \Xi_2^2\right)^{1/2}.$$

∎

The DF^J Test Statistic

The least square estimators of the standardized intercept and the autoregressive coefficients with regression (12) are

$$
\begin{bmatrix}
\tilde{\alpha} - \alpha_0 \\
\tilde{\phi}_1 - \phi_1 \\
\vdots \\
\tilde{\phi}_K - \phi_K \\
\tilde{\beta} - \beta_0
\end{bmatrix}
= \sigma \sqrt{\Delta}
\begin{bmatrix}
T & \sum I_{i\Delta}^1 & \cdots & \sum I_{i\Delta}^K & \sum y_{(i-1)\Delta} \\
\sum I_{i\Delta}^1 & \sum \left(I_{i\Delta}^1\right)^2 & \cdots & \sum I_{i\Delta}^1 I_{i\Delta}^K & \sum I_{i\Delta}^1 y_{(i-1)\Delta} \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
\sum I_{i\Delta}^K & \sum I_{i\Delta}^K I_{i\Delta}^1 & \cdots & \sum \left(I_{i\Delta}^K\right)^2 & \sum I_{i\Delta}^K y_{(i-1)\Delta} \\
\sum y_{(i-1)\Delta} & \sum y_{(i-1)\Delta} I_{i\Delta}^1 & \cdots & \sum y_{(i-1)\Delta} I_{i\Delta}^K & \sum y_{(i-1)\Delta}^2
\end{bmatrix}^{-1}
\begin{bmatrix}
\sum \varepsilon_{i\Delta} \\
\sum I_{i\Delta}^1 \varepsilon_{i\Delta} \\
\vdots \\
\sum I_{i\Delta}^K \varepsilon_{i\Delta} \\
\sum y_{(i-1)\Delta} \varepsilon_{i\Delta}
\end{bmatrix}.
$$

Let $\sum$ denote summation over $i = 1, \cdots, T$. Based on Lemma 3.1(d) and 3.2(d), the appropriate scaling matrix is $\Upsilon_{T_n} = diag\left(\sqrt{T}, 1, \cdots, 1, \sqrt{T}\right)$. Pre-multiplying the above equation by Υ_T leads to

$$
T^{1/2}\Upsilon_T
\begin{bmatrix}
\tilde{\alpha} - \alpha_0 \\
\tilde{\phi}_1 - \phi_1 \\
\vdots \\
\tilde{\phi}_K - \phi_K \\
\tilde{\beta} - \beta_0
\end{bmatrix}
= \sigma N^{1/2}
\left\{
\Upsilon_T^{-1}
\begin{bmatrix}
T & \sum I_{i\Delta}^1 & \cdots & \sum I_{i\Delta}^K & \sum y_{(i-1)\Delta} \\
\sum I_{i\Delta}^1 & \sum \left(I_{i\Delta}^1\right)^2 & \cdots & \sum I_{i\Delta}^1 I_{i\Delta}^K & \sum I_{i\Delta}^1 y_{(i-1)\Delta} \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
\sum I_{i\Delta}^K & \sum I_{i\Delta}^K I_{i\Delta}^1 & \cdots & \sum \left(I_{i\Delta}^K\right)^2 & \sum I_{i\Delta}^K y_{(i-1)\Delta} \\
\sum y_{(i-1)\Delta} & \sum y_{(i-1)\Delta} I_{i\Delta}^1 & \cdots & \sum y_{(i-1)\Delta} I_{i\Delta}^K & \sum y_{(i-1)\Delta}^2
\end{bmatrix}
\Upsilon_T^{-1}
\right\}^{-1}
$$

$$
\Upsilon_T^{-1}
\begin{bmatrix}
\sum \varepsilon_{i\Delta} \\
\sum I_{i\Delta}^1 \varepsilon_{i\Delta} \\
\vdots \\
\sum I_{i\Delta}^K \varepsilon_{i\Delta} \\
\sum y_{(i-1)\Delta} \varepsilon_{i\Delta}
\end{bmatrix}
$$

with $\alpha_0 = 0$ and $\beta_0 = 1$ under the null. The first term

$$
\Upsilon_T^{-1}
\begin{bmatrix}
T & \sum I_{i\Delta}^1 & \cdots & \sum I_{i\Delta}^K & \sum y_{(i-1)\Delta} \\
\sum I_{i\Delta}^1 & \sum \left(I_{i\Delta}^1\right)^2 & \cdots & \sum I_{i\Delta}^1 I_{i\Delta}^K & \sum I_{i\Delta}^1 y_{(i-1)\Delta} \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
\sum I_{i\Delta}^K & \sum I_{i\Delta}^K I_{i\Delta}^1 & \cdots & \sum \left(I_{i\Delta}^K\right)^2 & \sum I_{i\Delta}^K y_{(i-1)\Delta} \\
\sum y_{(i-1)\Delta} & \sum y_{(i-1)\Delta} I_{i\Delta}^1 & \cdots & \sum y_{(i-1)\Delta} I_{i\Delta}^K & \sum y_{(i-1)\Delta}^2
\end{bmatrix}
\Upsilon_T^{-1}
$$

$$
= \begin{bmatrix}
1 & T^{-1/2}\sum I_{i\Delta}^1 & \cdots & T^{-1/2}\sum I_{i\Delta}^K & T^{-1}\sum y_{(i-1)\Delta} \\
T^{-1/2}\sum I_{i\Delta}^1 & \sum\left(I_{i\Delta}^1\right)^2 & \cdots & \sum I_{i\Delta}^1 I_{i\Delta}^K & T^{-1/2}\sum I_{i\Delta}^1 y_{(i-1)\Delta} \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
T^{-1/2}\sum I_{i\Delta}^K & \sum I_{i\Delta}^K I_{i\Delta}^1 & \cdots & \sum\left(I_{i\Delta}^K\right)^2 & T^{-1/2}\sum I_{i\Delta}^K y_{(i-1)\Delta} \\
T^{-1}\sum y_{(i-1)\Delta} & T^{-1/2}\sum y_{(i-1)\Delta}I_{i\Delta}^1 & \cdots & T^{-1/2}\sum y_{(i-1)\Delta}I_{i\Delta}^K & T^{-1}\sum y_{(i-1)\Delta}^2
\end{bmatrix}
$$

$$
= \begin{bmatrix}
1 & T^{-1/2} & \cdots & T^{-1/2} & T^{-1}\sum y_{(i-1)\Delta} \\
T^{-1/2} & 1 & \cdots & 0 & T^{-1/2}y_{(\tau_1-1)\Delta} \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
T^{-1/2} & 0 & \cdots & 1 & T^{-1/2}y_{(\tau_K-1)\Delta} \\
T^{-1}\sum y_{(i-1)\Delta} & T^{-1/2}y_{(\tau_1-1)\Delta} & \cdots & T^{-1/2}y_{(\tau_K-1)\Delta} & T^{-1}\sum y_{(i-1)\Delta}^2
\end{bmatrix}.
$$

The second term

$$
\Upsilon_T^{-1}\begin{bmatrix}
\sum\varepsilon_{i\Delta} \\
\sum I_{i\Delta}^1\varepsilon_{i\Delta} \\
\vdots \\
\sum I_{i\Delta}^K\varepsilon_{i\Delta} \\
\sum y_{(i-1)\Delta}\varepsilon_{i\Delta}
\end{bmatrix} = \begin{bmatrix}
T^{-1/2}\sum\varepsilon_{i\Delta} \\
\sum I_{i\Delta}^1\varepsilon_{i\Delta} \\
\vdots \\
\sum I_{i\Delta}^K\varepsilon_{i\Delta} \\
T^{-1/2}\sum y_{(i-1)\Delta}\varepsilon_{i\Delta}
\end{bmatrix}.
$$

Proof of Theorem 3.1. Under the null hypothesis of (11), from Lemma 3.1 , the first term

$$
\Upsilon_T^{-1}\begin{bmatrix}
T & \sum I_{i\Delta}^1 & \cdots & \sum I_{i\Delta}^K & \sum y_{(i-1)\Delta} \\
\sum I_{i\Delta}^1 & \sum\left(I_{i\Delta}^1\right)^2 & \cdots & \sum I_{i\Delta}^1 I_{i\Delta}^K & \sum I_{i\Delta}^1 y_{(i-1)\Delta} \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
\sum I_{i\Delta}^K & \sum I_{i\Delta}^K I_{i\Delta}^1 & \cdots & \sum\left(I_{i\Delta}^K\right)^2 & \sum I_{i\Delta}^K y_{(i-1)\Delta} \\
\sum y_{(i-1)\Delta} & \sum y_{(i-1)\Delta}I_{i\Delta}^1 & \cdots & \sum y_{(i-1)\Delta}I_{i\Delta}^K & \sum y_{(i-1)\Delta}^2
\end{bmatrix}\Upsilon_T^{-1} \Rightarrow \begin{bmatrix}
1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Psi}_2 \\
0 & 1 & \cdots & 0 & 0 \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
0 & 0 & \cdots & 1 & 0 \\
\sigma N^{1/2}\tilde{\Psi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Psi}_3
\end{bmatrix}
$$

and the second term

$$
\Upsilon_T^{-1}\begin{bmatrix}
\sum\varepsilon_{i\Delta} \\
\sum I_{i\Delta}^1\varepsilon_{i\Delta} \\
\vdots \\
\sum I_{i\Delta}^K\varepsilon_{i\Delta} \\
\sum y_{(i-1)\Delta}\varepsilon_{i\Delta}
\end{bmatrix} \Rightarrow \begin{bmatrix}
w_1 \\
\varepsilon_{\tau_1} \\
\vdots \\
\varepsilon_{\tau_K} \\
\sigma N^{1/2}\tilde{\Psi}_4
\end{bmatrix}.
$$

Combining these two terms, we have

$$
\begin{bmatrix}
T\tilde{\alpha} \\
T^{1/2}\left(\tilde{\phi}_1 - \phi_1\right) \\
\vdots \\
T^{1/2}\left(\tilde{\phi}_K - \phi_K\right) \\
T\left(\tilde{\beta} - 1\right)
\end{bmatrix}
\Rightarrow \sigma N^{1/2}
\begin{bmatrix}
1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Psi}_2 \\
0 & 1 & \cdots & 0 & 0 \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
0 & 0 & \cdots & 1 & 0 \\
\sigma N^{1/2}\tilde{\Psi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Psi}_3
\end{bmatrix}^{-1}
\begin{bmatrix}
w_1 \\
\varepsilon_{\tau_1} \\
\vdots \\
\varepsilon_{\tau_K} \\
\sigma N^{1/2}\tilde{\Psi}_4
\end{bmatrix}
=
\begin{bmatrix}
\sigma N^{1/2}\frac{\tilde{\Psi}_3 w_1 - \tilde{\Psi}_2 \tilde{\Psi}_4}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2} \\
\sigma N^{1/2}\varepsilon_{\tau_1} \\
\vdots \\
\sigma N^{1/2}\varepsilon_{\tau_K} \\
\frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2}
\end{bmatrix}.
$$

Therefore,

$$
\begin{aligned}
T\tilde{\alpha} &\Rightarrow \sigma N^{1/2}\frac{\tilde{\Psi}_3 w_1 - \tilde{\Psi}_2 \tilde{\Psi}_4}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2} \\
T^{1/2}\left(\tilde{\phi}_k - \phi_k\right) &\Rightarrow \mathcal{N}\left(0, \sigma^2 N\right) \quad \text{for } k = 1, \ldots, K \\
T\left(\tilde{\beta} - 1\right) &\Rightarrow \frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2}.
\end{aligned}
$$

The estimated error variance

$$
\begin{aligned}
\tilde{\sigma}_v^2 &= \sum\left(y_{i\Delta} - \tilde{\beta}y_{(i-1)\Delta} - \tilde{\alpha} - \sum_{k=1}^{K}\tilde{\phi}_k I_{i\Delta}^k\right)^2 \\
&= \sum\left[\sigma\sqrt{\Delta}\varepsilon_{i\Delta} - \left(\tilde{\beta} - 1\right)y_{(i-1)\Delta} - \tilde{\alpha} + \sum_{k=1}^{K}\left(\tilde{\phi}_k - \phi_k\right)I_{i\Delta}^k\right]^2 \\
&= \sigma^2\Delta\sum\varepsilon_{i\Delta}^2 + \left(\tilde{\beta} - 1\right)^2\sum y_{(i-1)\Delta}^2 + \tilde{\alpha}^2 + \sum\left(\sum_{k=1}^{K}\left(\tilde{\phi}_k - \phi_k\right)I_{i\Delta}^k\right)^2 \\
&\quad -2\sigma\sqrt{\Delta}\left(\tilde{\beta} - 1\right)\sum y_{(i-1)\Delta}\varepsilon_{i\Delta} - 2\sigma\sqrt{\Delta}\tilde{\alpha}\sum\varepsilon_{i\Delta} + 2\sigma\sqrt{\Delta}\sum\left(\sum_{k=1}^{K}\left(\tilde{\phi}_k - \phi_k\right)I_{i\Delta}^k\right)\varepsilon_{i\Delta} \\
&\quad +2\left(\tilde{\beta} - 1\right)\tilde{\alpha}\sum y_{(i-1)\Delta} - 2\left(\tilde{\beta} - 1\right)\sum y_{(i-1)\Delta}\sum_{k=1}^{K}\left(\tilde{\phi}_k - \phi_k\right)I_{i\Delta}^k - 2\tilde{\alpha}\sum\sum_{k=1}^{K}\left(\tilde{\phi}_k - \phi_k\right)I_{i\Delta}^k \\
&= \sigma^2\Delta\sum\varepsilon_{i\Delta}^2\left[1 + o_p\left(1\right)\right] \to \sigma^2 N
\end{aligned}
$$

from Lemma 3.1 and the fact that $\tilde{\alpha} = O_p\left(T^{-1}\right)$, $\tilde{\beta} - 1 = O_p\left(T^{-1}\right)$, and $\tilde{\phi}_k - \phi_k = O_p\left(T^{-1/2}\right)$,

$$
DF^J = \frac{\left(\tilde{\beta} - 1\right)\left[T\sum_{j=1}^{T}y_{(j-1)\Delta}^2 - \left(\sum_{j=1}^{T}y_{(j-1)\Delta}\right)^2\right]^{1/2}}{\left[\sum_{j=1}^{T}\left(y_{j\Delta} - \tilde{\beta}y_{(j-1)\Delta} - \tilde{\alpha} - \sum_{k=1}^{K}\tilde{\phi}_k I_{j\Delta}^k\right)^2\right]^{1/2}} \Longrightarrow \frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1}{\left(\tilde{\Psi}_3 - \tilde{\Psi}_2^2\right)^{1/2}}.
$$

∎

Proof of Theorem 3.2. Under the alternative hypothesis of (10), from Lemma 3.2, the first term

$$
\Upsilon_T^{-1}
\begin{bmatrix}
T & \sum I_{i\Delta}^1 & \cdots & \sum I_{i\Delta}^K & \sum y_{(i-1)\Delta} \\
\sum I_{i\Delta}^1 & \sum \left(I_{i\Delta}^1\right)^2 & \cdots & \sum I_{i\Delta}^1 I_{i\Delta}^K & \sum I_{i\Delta}^1 y_{(i-1)\Delta} \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
\sum I_{i\Delta}^K & \sum I_{i\Delta}^K I_{i\Delta}^1 & \cdots & \sum \left(I_{i\Delta}^K\right)^2 & \sum I_{i\Delta}^K y_{(i-1)\Delta} \\
\sum y_{(i-1)\Delta} & \sum y_{(i-1)\Delta} I_{i\Delta}^1 & \cdots & \sum y_{(i-1)\Delta} I_{i\Delta}^K & \sum y_{(i-1)\Delta}^2
\end{bmatrix}
\Upsilon_T^{-1} \Rightarrow
\begin{bmatrix}
1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Xi}_2 \\
0 & 1 & \cdots & 0 & 0 \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
0 & 0 & \cdots & 1 & 0 \\
\sigma N^{1/2}\tilde{\Xi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Xi}_3
\end{bmatrix}
$$

and the second term

$$
\Upsilon_T^{-1}
\begin{bmatrix}
\sum \varepsilon_{i\Delta} \\
\sum I_{i\Delta}^1 \varepsilon_{i\Delta} \\
\vdots \\
\sum I_{i\Delta}^K \varepsilon_{i\Delta} \\
\sum y_{(i-1)\Delta} \varepsilon_{i\Delta}
\end{bmatrix}
\Rightarrow
\begin{bmatrix}
w_1 \\
\varepsilon_{\tau_1} \\
\vdots \\
\varepsilon_{\tau_K} \\
\sigma N^{1/2}\tilde{\Xi}_4
\end{bmatrix}.
$$

Combining these two terms, we have

$$
\begin{bmatrix}
T(\tilde{\alpha} - \alpha_0) \\
T^{1/2}\left(\tilde{\phi}_1 - \phi_1\right) \\
\vdots \\
T^{1/2}\left(\tilde{\phi}_K - \phi_K\right) \\
T\left(\tilde{\beta} - \beta_0\right)
\end{bmatrix}
\Rightarrow \sigma N^{1/2}
\begin{bmatrix}
1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Xi}_2 \\
0 & 1 & \cdots & 0 & 0 \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
0 & 0 & \cdots & 1 & 0 \\
\sigma N^{1/2}\tilde{\Xi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Xi}_3
\end{bmatrix}^{-1}
\begin{bmatrix}
w_1 \\
\varepsilon_{\tau_1} \\
\vdots \\
\varepsilon_{\tau_K} \\
\sigma N^{1/2}\tilde{\Xi}_4
\end{bmatrix}
=
\begin{bmatrix}
\sigma N^{1/2}\frac{\tilde{\Xi}_3 w_1 - \tilde{\Xi}_2 \tilde{\Xi}_4}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2} \\
\sigma N^{1/2}\varepsilon_{\tau_1} \\
\vdots \\
\sigma N^{1/2}\varepsilon_{\tau_K} \\
\frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2}
\end{bmatrix}.
$$

Similarly, we can show that the error variance $\tilde{\sigma}_v^2 = \sum \left(y_{i\Delta} - \tilde{\beta} y_{(i-1)\Delta} - \tilde{\alpha} - \sum_{k=1}^K \tilde{\phi}_k I_{i\Delta}^k\right)^2 = \sigma^2 \Delta \sum \varepsilon_{i\Delta}^2 \left[1 + o_p(1)\right] \to$
$\sigma^2 N$. From Lemma 3.2 and the results that $\tilde{\beta} - \beta_0 = O_p\left(T^{-1}\right)$

$$
\begin{aligned}
DF &= \frac{\left(\tilde{\beta} - 1\right)\left[T \sum_{j=1}^T y_{(j-1)\Delta}^2 - \left(\sum_{j=1}^T y_{(j-1)\Delta}\right)^2\right]^{1/2}}{\left[\sum_{j=1}^T \left(y_{j\Delta} - \tilde{\beta} y_{(j-1)\Delta} - \tilde{\alpha} - \sum_{k=1}^K \tilde{\phi}_k I_{j\Delta}^k\right)^2\right]^{1/2}} \\
&\Longrightarrow \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1}{\left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2\right)^{1/2}} + c\left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2\right)^{1/2}.
\end{aligned}
$$

∎

The DF Test Statistic in the Presence of Jumps

Proof of Theorem 3.3. The least square estimators of the standardized intercept and the autoregressive coefficients with regression (4), under the DGP of (11), are

$$
\begin{bmatrix} \hat{\alpha} \\ \hat{\beta} - 1 \end{bmatrix} = \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix}^{-1} \left(\begin{bmatrix} \sum_{k=1}^{K} \phi_k \sum I_{j\Delta}^k \\ \sum_{k=1}^{K} \phi_k \sum y_{(j-1)\Delta} I_{j\Delta}^k \end{bmatrix} + \sigma\sqrt{\Delta} \begin{bmatrix} \sum \varepsilon_{j\Delta} \\ \sum y_{(j-1)\Delta}\varepsilon_{j\Delta} \end{bmatrix} \right).
$$

Pre-multiplying the above equation by $\Upsilon_{T_n} = diag\left(\sqrt{T}, \sqrt{T}\right)$ leads to

$$
T^{1/2}\Upsilon_{T_n} \begin{bmatrix} \hat{\alpha} \\ \hat{\beta} - 1 \end{bmatrix}
$$

$$
= \left\{ \Upsilon_{T_n}^{-1} \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix} \Upsilon_{T_n}^{-1} \right\}^{-1} \begin{bmatrix} \sum_{k=1}^{K} \phi_k + \sigma\sqrt{\Delta}\sum \varepsilon_{j\Delta} \\ \sum_{k=1}^{K} \phi_k y_{(\tau_k-1)\Delta} + \sigma\sqrt{\Delta}\sum y_{(j-1)\Delta}\varepsilon_{j\Delta} \end{bmatrix}.
$$

The first term

$$
\Upsilon_{T_n}^{-1} \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix} \Upsilon_{T_n}^{-1} = \begin{bmatrix} T & T^{-1}\sum y_{(j-1)\Delta} \\ T^{-1}\sum y_{(j-1)\Delta} & T^{-1}\sum y_{(j-1)\Delta}^2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & \sigma N^{1/2}\tilde{\Psi}_2 \\ \sigma N^{1/2}\tilde{\Psi}_2 & \sigma^2 N\tilde{\Psi}_3 \end{bmatrix}.
$$

For the second term,

$$
\begin{bmatrix} \sum_{k=1}^{K} \phi_k + \sigma\sqrt{\Delta}\sum \varepsilon_{j\Delta} \\ \sum_{k=1}^{K} \phi_k y_{(\tau_k-1)\Delta} + \sigma\sqrt{\Delta}\sum y_{(j-1)\Delta}\varepsilon_{j\Delta} \end{bmatrix} = \begin{bmatrix} \sum_{k=1}^{K} \phi_k + \sigma N^{1/2}\left(T^{-1/2}\sum \varepsilon_{j\Delta}\right) \\ \sum_{k=1}^{K} \phi_k y_{(\tau_k-1)\Delta} + \sigma N^{1/2}\left(T^{-1/2}\sum y_{(j-1)\Delta}\varepsilon_{j\Delta}\right) \end{bmatrix}
$$

$$
\Rightarrow \begin{bmatrix} \sigma N^{1/2}\left(\sum_{k=1}^{K} \frac{\phi_k}{\sigma N^{1/2}} + w_1\right) \\ \sigma^2 N\left[\sum_{k=1}^{K} \frac{\phi_k}{\sigma N^{1/2}}\left(w_{r_k} + \gamma + \Delta_2\right) + \tilde{\Psi}_4\right] \end{bmatrix}.
$$

Combining these two terms, we have

$$
\begin{bmatrix} T\hat{\alpha} \\ T\left(\hat{\beta} - 1\right) \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & \sigma N^{1/2}\tilde{\Psi}_2 \\ \sigma N^{1/2}\tilde{\Psi}_2 & \sigma^2 N\tilde{\Psi}_3 \end{bmatrix}^{-1} \begin{bmatrix} \sigma N^{1/2}\left(\sum_{k=1}^{K} \frac{\phi_k}{\sigma N^{1/2}} + w_1\right) \\ \sigma^2 N\left[\sum_{k=1}^{K} \frac{\phi_k}{\sigma N^{1/2}}\left(w_{r_k} + \gamma + \Delta_2\right) + \tilde{\Psi}_4\right] \end{bmatrix}
$$

$$
= \begin{bmatrix} \sigma N^{1/2}\frac{\tilde{\Psi}_3 w_1 - \tilde{\Psi}_2\tilde{\Psi}_4 + \sum_{k=1}^{K} \frac{\phi_k}{\sigma N^{1/2}}\left[\tilde{\Psi}_3 - \tilde{\Psi}_2\left(w_{r_k}+\gamma+\Delta_2\right)\right]}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2} \\ \frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1 + \sum_{k=1}^{K} \frac{\phi_k}{\sigma N^{1/2}}\left(w_{r_k}+\gamma+\Delta_2-\tilde{\Psi}_2\right)}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2} \end{bmatrix}.
$$

Furthermore,

$$
\hat{\sigma}_v^2 = \sum \left(y_{j\Delta} - \hat{\beta}y_{(j-1)\Delta} - \hat{\alpha}\right)^2
$$

$$= \sum \left[\sigma\sqrt{\Delta}\varepsilon_{j\Delta} - \left(\hat{\beta}-1\right)y_{(j-1)\Delta} - \hat{\alpha} + \sum_{k=1}^{K}\phi_k I_{j\Delta}^k \right]^2$$

$$= \sigma^2\Delta\sum\varepsilon_j^2 + \left(\hat{\beta}-1\right)^2\sum y_{(j-1)\Delta}^2 + \hat{\alpha}^2 + \sum\left(\sum_{k=1}^{K}\phi_k I_{j\Delta}^k\right)^2$$

$$-2\sigma\sqrt{\Delta}\left(\hat{\beta}-1\right)\sum y_{(j-1)\Delta}\varepsilon_{j\Delta} - 2\sigma\sqrt{\Delta}\hat{\alpha}\sum\varepsilon_j + 2\sigma\sqrt{\Delta}\sum\left(\sum_{k=1}^{K}\phi_k I_{j\Delta}^k\right)\varepsilon_{j\Delta}$$

$$+2\left(\hat{\beta}-1\right)\hat{\alpha}\sum y_{(j-1)\Delta} - 2\left(\hat{\beta}-1\right)\sum y_{(j-1)\Delta}\sum_{k=1}^{K}\phi_k I_{j\Delta}^k - 2\hat{\alpha}\sum\sum_{k=1}^{K}\phi_k I_{j\Delta}^k$$

$$= \left[\sigma^2\Delta\sum\varepsilon_j^2 + \sum\left(\sum_{k=1}^{K}\phi_k I_{j\Delta}^k\right)^2\right]\{1+o_p(1)\}$$

$$\to \sigma^2 N\left(1+\sum_{k=1}^{K}\frac{\phi_k^2}{\sigma^2 N}\right)$$

from Lemma 3.1 and the fact that $\tilde{\alpha} = O_p\left(T^{-1}\right)$, and $\tilde{\beta}-1 = O_p\left(T^{-1}\right)$. The DF statistic is

$$DF = \frac{\left(\hat{\beta}-1\right)\left[T\sum_{j=1}^{T}y_{(j-1)\Delta}^2 - \left(\sum_{j=1}^{T}y_{(j-1)\Delta}\right)^2\right]^{1/2}}{\left[\sum_{j=1}^{T}\left(y_{j\Delta}-\hat{\alpha}-\hat{\beta}y_{(j-1)\Delta}\right)^2\right]^{1/2}}$$

$$\Longrightarrow \left[\frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2} + \frac{\sum_{k=1}^{K}\frac{\phi_k}{\sigma N^{1/2}}\left(w_{r_k}+\gamma+\Delta_2-\tilde{\Psi}_2\right)}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2}\right]\left(\frac{\tilde{\Psi}_3-\tilde{\Psi}_2^2}{1+\sum_{k=1}^{K}\frac{\phi_k^2}{\sigma^2 N}}\right)^{1/2}$$

$$= \frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1 + \sum_{k=1}^{K}\frac{\phi_k}{\sigma N^{1/2}}\left(w_{r_k}+\gamma+\Delta_2-\tilde{\Psi}_2\right)}{\left(1+\sum_{k=1}^{K}\frac{\phi_k^2}{\sigma^2 N}\right)^{1/2}\left(\tilde{\Psi}_3-\tilde{\Psi}_2^2\right)^{1/2}}.$$

∎

Proof of Theorem 3.4. The least square estimators of the standardized intercept and the autoregressive coefficients with regression (4), under the DGP of (10), are

$$\begin{bmatrix} \hat{\alpha}-\alpha_0 \\ \hat{\beta}-\beta_0 \end{bmatrix} = \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix}^{-1}$$

$$\left(\begin{bmatrix} \sum_{k=1}^{K}\phi_k\sum I_{j\Delta}^k \\ \sum_{k=1}^{K}\phi_k\sum y_{(j-1)\Delta}I_{j\Delta}^k \end{bmatrix} + \lambda_0\begin{bmatrix} \sum\varepsilon_{j\Delta} \\ \sum y_{(j-1)\Delta}\varepsilon_{j\Delta} \end{bmatrix}\right).$$

Pre-multiplying the above equation by $\Upsilon_{T_n} = diag\left(\sqrt{T},\sqrt{T}\right)$ leads to

$$T^{1/2}\Upsilon_{T_n}\begin{bmatrix} \hat{\alpha}-\alpha_0 \\ \hat{\beta}-\beta_0 \end{bmatrix}$$

$$= \left\{ \Upsilon_{T_n}^{-1} \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix} \Upsilon_{T_n}^{-1} \right\}^{-1} \begin{bmatrix} \sum_{k=1}^K \phi_k + \lambda_0 \sum \varepsilon_{j\Delta} \\ \sum_{k=1}^K \phi_k y_{(\tau_k-1)\Delta} + \lambda_0 \sum y_{(j-1)\Delta} \varepsilon_{j\Delta} \end{bmatrix}.$$

The first term

$$\Upsilon_{T_n}^{-1} \begin{bmatrix} T & \sum y_{(j-1)\Delta} \\ \sum y_{(j-1)\Delta} & \sum y_{(j-1)\Delta}^2 \end{bmatrix} \Upsilon_{T_n}^{-1} = \begin{bmatrix} T & T^{-1} \sum y_{(j-1)\Delta} \\ T^{-1} \sum y_{(j-1)\Delta} & T^{-1} \sum y_{(j-1)\Delta}^2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & \sigma N_2^{1/2} \tilde{\Xi}_2 \\ \sigma N^{1/2} \tilde{\Xi}_2 & \sigma^2 N \tilde{\Xi}_3 \end{bmatrix}.$$

For the second term,

$$\begin{bmatrix} \sum_{k=1}^K \phi_k + \lambda_0 \sum \varepsilon_{j\Delta} \\ \sum_{k=1}^K \phi_k y_{(\tau_k-1)\Delta} + \lambda_0 \sum y_{(j-1)\Delta} \varepsilon_{j\Delta} \end{bmatrix} = \begin{bmatrix} \sum_{k=1}^K \phi_k + T^{1/2} \lambda_0 \left(T^{-1/2} \sum \varepsilon_{j\Delta} \right) \\ \sum_{k=1}^K \phi_k y_{(\tau_k-1)\Delta} + T^{1/2} \lambda_0 \left(T^{-1/2} \sum y_{(j-1)\Delta} \varepsilon_{j\Delta} \right) \end{bmatrix}$$

$$\implies \begin{bmatrix} \sigma N^{1/2} \left(\sum_{k=1}^K \varsigma_k + w_1 \right) \\ \sigma^2 N \left\{ \sum_{k=1}^K \varsigma_k \left[\delta \left(1 - e^{r_k c} \right) + J_c \left(r_k \right) + e^{r_k c} \gamma + \Delta_4 \right] + \tilde{\Xi}_4 \right\} \end{bmatrix}.$$

Combining these two terms, we have

$$\begin{bmatrix} T \left(\hat{\alpha} - \alpha_0 \right) \\ T \left(\hat{\beta} - \beta_0 \right) \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & \sigma N_2^{1/2} \tilde{\Xi}_2 \\ \sigma N_2^{1/2} \tilde{\Xi}_2 & \sigma^2 N \tilde{\Xi}_3 \end{bmatrix}^{-1} \begin{bmatrix} \sigma N^{1/2} \left(\sum_{k=1}^K \varsigma_k + w_1 \right) \\ \sigma^2 N \left\{ \sum_{k=1}^K \varsigma_k \left[\delta \left(1 - e^{r_k c} \right) + J_c \left(r_k \right) + e^{r_k c} \gamma + \Delta_4 \right] + \tilde{\Xi}_4 \right\} \end{bmatrix}$$

$$= \begin{bmatrix} \sigma N^{1/2} \frac{\tilde{\Xi}_3 w_1 - \tilde{\Xi}_2 \tilde{\Xi}_4 + \sum_{k=1}^K \varsigma_k \left[\tilde{\Xi}_3 - \left[\delta \left(1 - e^{r_k c} \right) + J_c(r_k) + e^{r_k c} \gamma + \Delta_4 \right] \tilde{\Xi}_2 \right]}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2} \\ \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1 + \sum_{k=1}^K \varsigma_k \left[\delta \left(1 - e^{r_k c} \right) + J_c(r_k) + e^{r_k c} \gamma + \Delta_4 - \tilde{\Xi}_2 \right]}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2} \end{bmatrix}.$$

Furthermore,

$$\begin{aligned} \hat{\sigma}_v^2 &= \sum \left(y_{j\Delta} - \hat{\beta} y_{(j-1)\Delta} - \hat{\alpha} \right)^2 \\ &= \sum \left[\lambda_0 \varepsilon_{j\Delta} - \left(\hat{\beta} - \beta_0 \right) y_{(j-1)\Delta} - \left(\hat{\alpha} - \alpha_0 \right) + \sum_{k=1}^K \phi_k I_{j\Delta}^k \right]^2 \\ &= \lambda_0^2 \sum \varepsilon_j^2 + \left(\hat{\beta} - \beta_0 \right)^2 \sum y_{(j-1)\Delta}^2 + \left(\hat{\alpha} - \alpha_0 \right)^2 + \sum \left(\sum_{k=1}^K \phi_k I_{j\Delta}^k \right)^2 \\ &\quad - 2\lambda_0 \left(\hat{\beta} - \beta_0 \right) \sum y_{(j-1)\Delta} \varepsilon_{j\Delta} - 2\lambda_0 \left(\hat{\alpha} - \alpha_0 \right) \sum \varepsilon_j + 2\lambda_0 \sum \left(\sum_{k=1}^K \phi_k I_{j\Delta}^k \right) \varepsilon_{j\Delta} \\ &\quad + 2 \left(\hat{\beta} - 1 \right) \left(\hat{\alpha} - \alpha_0 \right) \sum y_{(j-1)\Delta} - 2 \left(\hat{\beta} - 1 \right) \sum y_{(j-1)\Delta} \sum_{k=1}^K \phi_k I_{j\Delta}^k - 2 \left(\hat{\alpha} - \alpha_0 \right) \sum \sum_{k=1}^K \phi_k I_{j\Delta}^k \\ &= \left[\lambda_0^2 \sum \varepsilon_j^2 + \sum \left(\sum_{k=1}^K \phi_k I_{j\Delta}^k \right)^2 \right] \left\{ 1 + o_p \left(1 \right) \right\} \end{aligned}$$

$$\to \quad \sigma^2 N \left(1 + \sum_{k=1}^{K} \frac{\phi_k^2}{\sigma^2 N}\right)$$

from Lemma 3.1 and the fact that $\tilde{\alpha} = O_p\left(T^{-1}\right)$, and $\tilde{\beta} - 1 = O_p\left(T^{-1}\right)$. The DF statistic is

$$
\begin{aligned}
DF \quad &= \quad \frac{\left(\hat{\beta} - 1\right)\left[T \sum_{j=1}^{T} y_{(j-1)\Delta}^2 - \left(\sum_{j=1}^{T} y_{(j-1)\Delta}\right)^2\right]^{1/2}}{\left[\sum_{j=1}^{T}\left(y_{j\Delta} - \hat{\alpha} - \hat{\beta}y_{(j-1)\Delta}\right)^2\right]^{1/2}} \\[2em]
&\Longrightarrow \quad \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1 + \sum_{k=1}^{K} \varsigma_k \left[\delta\left(1 - e^{r_k c}\right) + J_c\left(r_k\right) + e^{r_k c}\gamma + \Delta_4 - \tilde{\Xi}_2\right]}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2} \left(\frac{\tilde{\Xi}_3 - \tilde{\Xi}_2^2}{1 + \sum_{k=1}^{K} \frac{\phi_k^2}{\sigma^2 N}}\right)^{1/2} + c\left(\frac{\tilde{\Xi}_3 - \tilde{\Xi}_2^2}{1 + \sum_{k=1}^{K} \frac{\phi_k^2}{\sigma^2 N}}\right)^{1/2} \\[2em]
&= \quad \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1 + \sum_{k=1}^{K} \varsigma_k \left[\delta\left(1 - e^{r_k c}\right) + J_c\left(r_k\right) + e^{r_k c}\gamma + \Delta_4 - \tilde{\Xi}_2\right]}{\left(1 + \sum_{k=1}^{K} \frac{\phi_k^2}{\sigma^2 N}\right)^{1/2}\left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2\right)^{1/2}} + c\left(\frac{\tilde{\Xi}_3 - \tilde{\Xi}_2^2}{1 + \sum_{k=1}^{K} \frac{\phi_k^2}{\sigma^2 N}}\right)^{1/2}.
\end{aligned}
$$

∎

Asymptotics of the $DF^{\hat{J}}$ statistic

Proof of Theorem 3.5. The null and alternative models can be written in matrix form as follows:

$$Y = X\theta^0 + \sigma\sqrt{\Delta}\varepsilon \text{ and } Y = X\theta^1 + \lambda_0\varepsilon,$$

where $Y = [y_{1\Delta}, y_{2\Delta}, \cdots, y_{T\Delta}]'$, $x_{i\Delta} = \left[1, I_{i\Delta}^1, \ldots, I_{i\Delta}^K, y_{(i-1)\Delta}\right]'$, $X = [x_{1\Delta}, x_{2\Delta}, \ldots, x_{T\Delta}]'$, $\theta^0 = (0, \phi_1, \ldots, \phi_K, 1)'$, $\theta^1 = (\alpha_0, \phi_1, \ldots, \phi_K, \beta_0)'$, $\varepsilon = [\varepsilon_{1\Delta}, \varepsilon_{2\Delta}, \cdots, \varepsilon_{T\Delta}]'$. The regression model is

$$Y = \hat{X}\theta + v,$$

where $\hat{x}_{i\Delta} = \left[1, \hat{I}_{i\Delta}^1, \ldots, \hat{I}_{i\Delta}^{\hat{K}}, y_{(i-1)\Delta}\right]'$, $\hat{X} = [\hat{x}_{1\Delta}, \hat{x}_{2\Delta}, \ldots, \hat{x}_{T\Delta}]'$, $\theta = \left(\alpha, \phi_1, \ldots, \phi_{\hat{K}}, \beta\right)'$, and $v = (v_{1\Delta}, v_{2\Delta}, \ldots, v_{T\Delta})'$. Let $\ddot{\theta} = \left(\ddot{\alpha}, \ddot{\phi}_1, \ldots, \ddot{\phi}_{\hat{K}}, \ddot{\beta}\right)'$ be the OLS estimate of θ. We have

$$\ddot{\theta} = \left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'Y = \left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'X\theta^0 + \sigma\sqrt{\Delta}\left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'\varepsilon$$

under the null and

$$\ddot{\theta} = \left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'Y = \left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'X\theta^1 + \lambda_0\left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'\varepsilon$$

under the alternative. Let $\Upsilon_T = diag\left(\sqrt{T}, 1, \cdots, 1, \sqrt{T}\right)$ and $\Upsilon_T^* = T^{1/2}\Upsilon_T$. We have

$$\Upsilon_T^{*-1}\hat{X}'\hat{X} = \begin{bmatrix} 1 & T^{-1}\sum \hat{I}_{i\Delta}^1 & \cdots & T^{-1}\sum \hat{I}_{i\Delta}^{\hat{K}} & T^{-1}\sum y_{(i-1)\Delta} \\ T^{-1/2}\sum \hat{I}_{i\Delta}^1 & T^{-1/2}\sum \left(\hat{I}_{i\Delta}^1\right)^2 & \cdots & T^{-1/2}\sum \hat{I}_{i\Delta}^1\hat{I}_{i\Delta}^{\hat{K}} & T^{-1/2}\sum \hat{I}_{i\Delta}^1 y_{(i-1)\Delta} \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} & T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}}\hat{I}_{i\Delta}^1 & \cdots & T^{-1/2}\sum \left(\hat{I}_{i\Delta}^{\hat{K}}\right)^2 & T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} y_{(i-1)\Delta} \\ T^{-1}\sum y_{(i-1)\Delta} & T^{-1}\sum y_{(i-1)\Delta}\hat{I}_{i\Delta}^1 & \cdots & T^{-1}\sum y_{(i-1)\Delta}\hat{I}_{i\Delta}^{\hat{K}} & T^{-1}\sum y_{(i-1)\Delta}^2 \end{bmatrix},$$

$$\Upsilon_T^{*-1}\hat{X}'X = \begin{bmatrix} 1 & T^{-1}\sum I_{i\Delta}^1 & \cdots & T^{-1}\sum I_{i\Delta}^K & T^{-1}\sum y_{(i-1)\Delta} \\ T^{-1/2}\sum \hat{I}_{i\Delta}^1 & T^{-1/2}\sum \hat{I}_{i\Delta}^1 I_{i\Delta}^1 & \cdots & T^{-1/2}\sum \hat{I}_{i\Delta}^1 I_{i\Delta}^K & T^{-1/2}\sum \hat{I}_{i\Delta}^1 y_{(i-1)\Delta} \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} & T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} I_{i\Delta}^1 & \cdots & T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} I_{i\Delta}^K & T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} y_{(i-1)\Delta} \\ T^{-1}\sum y_{(i-1)\Delta} & T^{-1}\sum y_{(i-1)\Delta} I_{i\Delta}^1 & \cdots & T^{-1}\sum y_{(i-1)\Delta} I_{i\Delta}^K & T^{-1}\sum y_{(i-1)\Delta}^2 \end{bmatrix},$$

and

$$\Upsilon_T^{-1}\hat{X}'\hat{X}\Upsilon_T^{-1} = \begin{bmatrix} 1 & T^{-1/2}\sum \hat{I}_{i\Delta}^1 & \cdots & T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} & T^{-1}\sum y_{(i-1)\Delta} \\ T^{-1/2}\sum \hat{I}_{i\Delta}^1 & \sum \left(\hat{I}_{i\Delta}^1\right)^2 & \cdots & \sum \hat{I}_{i\Delta}^1\hat{I}_{i\Delta}^{\hat{K}} & T^{-1/2}\sum \hat{I}_{i\Delta}^1 y_{(i-1)\Delta} \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} & \sum \hat{I}_{i\Delta}^{\hat{K}}\hat{I}_{i\Delta}^1 & \cdots & \sum \left(\hat{I}_{i\Delta}^{\hat{K}}\right)^2 & T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} y_{(i-1)\Delta} \\ T^{-1}\sum y_{(i-1)\Delta} & T^{-1/2}\sum \hat{I}_{i\Delta}^1 y_{(i-1)\Delta} & \cdots & T^{-1/2}\sum \hat{I}_{i\Delta}^{\hat{K}} y_{(i-1)\Delta} & T^{-1}\sum y_{(i-1)\Delta}^2 \end{bmatrix}.$$

By construction, we have $\sum I_{i\Delta}^k = 1$, $\sum \hat{I}_{i\Delta}^k = 1$, $\sum I_{i\Delta}^s I_{i\Delta}^l = 0$, and $\sum \hat{I}_{i\Delta}^s \hat{I}_{i\Delta}^l = 0$ for any $s, l, k \in \left[1, \hat{K}\right]$ and $s \neq l$. (1) Under the null hypothesis of (11),

$$\Upsilon_T^{*-1}\hat{X}'\hat{X} \implies \begin{bmatrix} 1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Psi}_2 \\ 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \\ \sigma N^{1/2}\tilde{\Psi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Psi}_3 \end{bmatrix}_{(K+2)\times(K+2)},$$

$$\Upsilon_T^{*-1}\hat{X}'X \implies \begin{bmatrix} 1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Psi}_2 \\ 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \\ \sigma N^{1/2}\tilde{\Psi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Psi}_3 \end{bmatrix}_{(K+2)\times(K+2)},$$

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$$
\Upsilon_T^{-1}\hat{X}'\hat{X}\Upsilon_T^{-1} \implies
\begin{bmatrix}
1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Psi}_2 \\
0 & 1 & \cdots & 0 & 0 \\
\vdots & \vdots & \cdots & \vdots & \vdots \\
0 & 0 & \cdots & 1 & 0 \\
\sigma N^{1/2}\tilde{\Psi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Psi}_3
\end{bmatrix}_{(K+2)\times(K+2)}
$$

using results from Lemma 3.1. Therefore,

$$
\ddot{\theta} = \left(\Upsilon_T^{*-1}\hat{X}'\hat{X}\right)^{-1}\left(\Upsilon_T^{*-1}\hat{X}'X\right)\theta^0 + \sigma\sqrt{\Delta}\left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'\varepsilon \sim \theta^0 + \sigma\sqrt{\Delta}\left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'\varepsilon.
$$

Furthermore,

$$
T^{1/2}\Upsilon_T^{-1}\sigma\sqrt{\Delta}\hat{X}'\varepsilon = T^{1/2}\sigma\sqrt{\Delta}
\begin{bmatrix}
T^{-1/2}\sum \varepsilon_{i\Delta} \\
\varepsilon_{\hat{\tau}_1\Delta} \\
\vdots \\
\varepsilon_{\hat{\tau}_k\Delta} \\
T^{-1/2}\sum y_{(i-1)\Delta}\varepsilon_{i\Delta}
\end{bmatrix}
\implies \sigma N^{1/2}
\begin{bmatrix}
w_1 \\
\varepsilon_{\tau_1\Delta} \\
\vdots \\
\varepsilon_{\tau_k\Delta} \\
\sigma N^{1/2}\tilde{\Psi}_4
\end{bmatrix}
$$

using results from Lemma 3.1 and Remark 3.2. Therefore,

$$
T^{1/2}\Upsilon_T\left(\ddot{\theta}-\theta^0\right) \sim T^{1/2}\sigma\sqrt{\Delta}\left(\Upsilon_T^{-1}\hat{X}'\hat{X}\Upsilon_T^{-1}\right)^{-1}\Upsilon_T^{-1}\hat{X}'\varepsilon \implies
\begin{bmatrix}
\sigma N^{1/2}\frac{\tilde{\Psi}_3 w_1 - \tilde{\Psi}_2\tilde{\Psi}_4}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2} \\
\sigma N^{1/2}\varepsilon_{\tau_1} \\
\vdots \\
\sigma N^{1/2}\varepsilon_{\tau_K} \\
\frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2}
\end{bmatrix}.
$$

More explicitly, we have

$$
\begin{aligned}
T\ddot{\alpha} &\implies \sigma N^{1/2}\frac{\tilde{\Psi}_3 w_1 - \tilde{\Psi}_2\tilde{\Psi}_4}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2}; \\
T^{1/2}\left(\ddot{\phi}_k - \phi_k\right) &\implies \mathcal{N}(0,\sigma^2 N); \\
T\left(\ddot{\beta}-1\right) &\implies \frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1}{\tilde{\Psi}_3 - \tilde{\Psi}_2^2}.
\end{aligned}
$$

(2) Under the alternative of (10)

$$\Upsilon_T^{*-1}\hat{X}'\hat{X} \implies \begin{bmatrix} 1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Xi}_2 \\ 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \\ \sigma N^{1/2}\tilde{\Xi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Xi}_3 \end{bmatrix}_{(K+2)\times(K+2)},$$

$$\Upsilon_T^{*-1}\hat{X}'X \implies \begin{bmatrix} 1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Xi}_2 \\ 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \\ \sigma N^{1/2}\tilde{\Xi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Xi}_3 \end{bmatrix}_{(K+2)\times(K+2)},$$

$$\Upsilon_T^{-1}\hat{X}'\hat{X}\Upsilon_T^{-1} \implies \begin{bmatrix} 1 & 0 & \cdots & 0 & \sigma N^{1/2}\tilde{\Xi}_2 \\ 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \\ \sigma N^{1/2}\tilde{\Xi}_2 & 0 & \cdots & 0 & \sigma^2 N\tilde{\Xi}_3 \end{bmatrix}_{(K+2)\times(K+2)}$$

using results from Lemma 3.2. Therefore,

$$\ddot{\theta} = \left(\Upsilon_T^{*-1}\hat{X}'\hat{X}\right)^{-1}\left(\Upsilon_T^{*-1}\hat{X}'X\right)\theta^1 + \lambda_0\left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'\varepsilon \sim \theta^1 + \lambda_0\left(\hat{X}'\hat{X}\right)^{-1}\hat{X}'\varepsilon.$$

Furthermore,

$$T^{1/2}\Upsilon_T^{-1}\lambda_0\hat{X}'\varepsilon = T^{1/2}\lambda_0 \begin{bmatrix} T^{-1/2}\sum\varepsilon_{i\Delta} \\ \varepsilon_{\hat{\tau}_1\Delta} \\ \vdots \\ \varepsilon_{\hat{\tau}_k\Delta} \\ T^{-1/2}\sum y_{(i-1)\Delta}\varepsilon_{i\Delta} \end{bmatrix} \implies \sigma N^{1/2}\begin{bmatrix} w_1 \\ \varepsilon_{\tau_1\Delta} \\ \vdots \\ \varepsilon_{\tau_k\Delta} \\ \sigma N^{1/2}\tilde{\Xi}_4 \end{bmatrix}$$

using results from Lemma 3.2 and Remark 3.2. Therefore, we have

$$T^{1/2}\Upsilon_T\left(\ddot{\theta}-\theta^1\right) \sim T^{1/2}\lambda_0\left(\Upsilon_T^{-1}\hat{X}'\hat{X}\Upsilon_T^{-1}\right)^{-1}\Upsilon_T^{-1}\hat{X}'\varepsilon \implies \begin{bmatrix} \sigma N^{1/2}\frac{\tilde{\Xi}_3 w_1 - \tilde{\Xi}_2\tilde{\Xi}_4}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2} \\ \sigma N^{1/2}\varepsilon_{\tau_1} \\ \vdots \\ \sigma N^{1/2}\varepsilon_{\tau_K} \\ \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2} \end{bmatrix}$$

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under the alternative. That is,

$$
\begin{aligned}
T\left(\ddot{\alpha} - \alpha_0\right) &\implies \sigma N^{1/2} \frac{\tilde{\Xi}_3 w_1 - \tilde{\Xi}_2 \tilde{\Xi}_4}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2}; \\
T^{1/2}\left(\ddot{\phi}_k - \phi_k\right) &\implies \mathcal{N}(0, \sigma^2 N); \\
T\left(\ddot{\beta} - \beta_0\right) &\implies \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1}{\tilde{\Xi}_3 - \tilde{\Xi}_2^2}.
\end{aligned}
$$

One can see that the limiting properties of $\ddot{\theta}$ are identical to those of $\tilde{\theta} = \left(\tilde{\alpha}, \tilde{\phi}_1, \ldots, \tilde{\phi}_{\hat{K}}, \tilde{\beta}\right)'$ under both the null and the alternative. The remaining part of the proof is analogous to those in Theorem 3.1 and 3.2. That is, $\ddot{\sigma}_v^2 \to \sigma^2 N$ under both the null and alternative hypotheses,

$$
DF^{\hat{J}} \implies \frac{\tilde{\Psi}_4 - \tilde{\Psi}_2 w_1}{\left(\tilde{\Psi}_3 - \tilde{\Psi}_2^2\right)^{1/2}}
$$

under the null hypothesis, and

$$
DF^{\hat{J}} \implies \frac{\tilde{\Xi}_4 - \tilde{\Xi}_2 w_1}{\left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2\right)^{1/2}} + c \left(\tilde{\Xi}_3 - \tilde{\Xi}_2^2\right)^{1/2}
$$

under the alternative. ∎

Supplementary Material

Laurent and Shi (2021): Supplement to "Unit root test with high-frequency data", Econometric Theory Supplementary Material. To view, please visit: [doi will be inserted here by typesetter]

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